# Honeywell 

## MAINTENANCE MANUAL

## BENDIX/KING ${ }^{\circledR}$

KI 525
PICTORIAL NAVIGATION INDICATOR

MANUAL NUMBER 006-15620-0007 REVISION 7 JULY, 2001

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# Honeywell 

## MAINTENANCE MANUAL

## BENDIX/KING

## KI 525

PICTORIAL NAVIGATION INDICATOR

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| ITEM | ACTION |
| :--- | :--- |
| All pages | Full Reprint, new manual |

Revision 7 creates a new stand-alone manual for the KI 525 which was extracted from revision 6 of the KCS 55/55A maintenance manual, (P/N 006-05111-0006). Any revisions to the KI 525, beginning with revision 7 , will not be a part of the KCS 55/55A manual.

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## SECTION IV THEORY OF OPERATION

### 4.1 GENERAL INFORMATION

### 4.1.1 <br> GENERAL DESCRIPTION

The KI 525 Pictorial Navigation Indicator consists of several functional sections. These include digitally driven heading display card, course datum and heading select optically derived autopilot outputs, a servo driven glideslope pointer using an optical position sensor, a glideslope retract circuit to detect an invalid GS signal, a NAV flag circuit that monitors NAV receiver power and video signal level, a system power flag along with the normal course deviation bar, TO-FROM meter, slaving CT, heading transmitter (on 066-03029-0001 units only) and course resolver.

### 4.2 HEADING DISPLAY CARD

A digital stepper motor is used to drive the heading display card in response to signals generated in the KG 102 directional gyro. These signals consist of a two phase excitation drive that is connected to the four stepper motor leads as shown in Figure 4-1.


FIGURE 4-1 STEPPER MOTOR DRIVE CIRCUIT
Each time the $A$ or $B$ waveforms change state, the motor shaft moves nine degrees in a direction determined by the previous state of the $A$ and $B$ waveforms. This motion is reduced to $1 / 4$ degree card rotation by a 36:1 gear train assembly.

### 4.3 G.S. POINTER

Operation of the GS pointer is based on the repulsion of a permanent magnet by an electromagnetic field. The mechanism used to operate the pointer is shown in Figure 4-2. In the quiescent, power off condition, the north and south poles of the circular magnet, which are rigidly attached to the pointer assembly, are attracted to the metal pole pieces at $A$ and $B$ respectively. This attraction causes the pointer to deflect upward behind the front bezel and out of sight. Therefore, the GS invalid signal needs only to remove the pointer drive signal in order to remove the pointer from view.


FIGURE 4-2 GS POINTER MECHANISM

### 4.3.1 GS POINTER DETAILED OPERATION

The glideslope deviation signal is connected to the KI 525 at pins B and E on the lower connector and from there to the P.C. board where resistors R139, R140 and R138 present a standard 1K ohm load to the receiver. (See Figure 4-3). These resistors are connected to differential amplifier 1103A where a gain of approximately sixty is achieved. From there, the signal passes through resistor R142 and thence to amplifier I103B where it is filtered by the RC network of resistor R165 and capacitors C108 and C109. This filtered signal is limited to -8.7 v by the combination of forward biased diode CR107 and reverse biased zener diode CR114. This limiting action is required to prevent the GS pointer from deflection up out of view behind the retract shroud during normal operation. Only when a GS invalid signal is present will the pointer disappear from view.

After being amplified, filtered and limited, the command signal passes through resistor R166 to amplifier I105B where it enters the glideslope pointer servo loop. (Figure 4-4)


FIGURE 4-3 GLIDESLOPE DEVIATION INPUT CIRCUITRY

Any signal present at the input of I105B will result in a ramping voltage at the output, the rate of which is determined by the magnitude of the input voltage, resistor R160, and capacitors C101 and C102. Positive inputs result in a negative moving ramps and negative inputs result in positive moving ramps. This ramping voltage passes through resistor R159 to low-pass filter consisting of I 105A resistor R 156 and R 157 , and capacitor C 103. The output of 1105A is connected through R153 to Q109 which forms an emitter follower consisting of resistor R154 and the GS pointer excitation coil. Diode CR106 protects Q109 during the glideslope retract mode of operation and diode CR116 prevents large reverse voltages from developing across the coil when Q109 shuts off. (Figure 4-4).

As the current builds up in the GS excitation coil, poles A and B (Figure 4-2) become magnetized NORTH and SOUTH respectively. This creates a repulsive force on the circular magnet attached to the GS pointer causing it to deflect in a downward direction. This motion causes the infrared light beam generated by LED CR117 to move laterally across the face of dual photocell V101. (Figure 4-5). The lateral motion is caused by the offset slit in the glideslope pointer assembly as shown in the figure, the left side of the photocell will be illuminated to a greater degree than the right side causing the center top of the photocell to become positive. Amplifier I106B compares this voltage with a reference value at the junction of resistors R143 and R144 and is produced by the voltages at each end of the photocell. In this way, variations in the photocell excitation voltages will not result in an offset at the output of I106B. The combination of resistor R104 and zener CR105 produce the +10VDC photocell voltage, and R105 and CR110 produce the -10VDC photocell voltage. From the output of I106B, the signal passes to a lead circuit consisting of resistors R149, R150 and E151 and capacitors C105 and C106. From the output of I106A, the signal passes to another lead circuit consisting of resistors R161 and R162 and capacitors C104 and C107. These lead circuits are required to compensate for the inherent lag in the glideslope pointer assembly and the photocell. The signal at this point is negative, having been inverted by amplifier I106A and tends to cancel the positive voltage produced by the command signal from amplifier I103B discussed above. When this cancellation occurs, the glideslope pointer stops moving and displays the aircraft location relative to the glideslope beam.

### 4.3.2 GS RETRACT CIRCUIT (Figure 4-6)

As the glideslope signal becomes weaker, the valid signal at bottom connector pin J and top connector pin W begins to decrease. This valid signal from the glideslope receiver is connected to resistors R126, R127 and R125 which represent a 1000ohm load to the receiver. Amplifier 1104A increases the amplitude of the valid signal by approximately forty and drives a level sensing circuit consisting of resistors R129, R130, R131; capacitor C110 and amplifier I104B. Capacitor C110 provides negative rate feedback to cause the circuit to operate as an integrator when the output of I104A becomes more positive than the switching point of I104B. The switching level is established by resistors R129 and E130 at approximately -7. 8VDC. When reduced by a factor of forty, this switching level corresponds to a level of 0.195VDC at the glideslope receiver. Since amplifier I104A uses negative feedback, the output of this stage is negative, thus requiring the negative bias voltage on amplifier I104B. When the output of I104A exceeds -7 . 8VDC, amplifier I104B slowly changes state from +15VDC to -15VDC. While amplifier I104B is in the -15VDC condition, the glideslope receiver is invalid resulting in current flow through forward biased diode CR109 and resistor R134. This negative current will overwhelm any current through resistor R162 or R166 resulting from the photocell or command signal and cause amplifier I105B to saturate at +15VDC. This voltage will cause amplifier I105A to saturate at -15VDC and force transistor Q109 to shut off and allow the glideslope pointer to deflect up and out of view.
As the glideslope valid voltage exceeds 0 . 195VDC, amplifier 1104B will slowly switch to +15VDC causing diode CR109 to be reversed biased, preventing current from flowing through resistor R 134. In this configuration, the glideslope pointer will drop into view and conform to the glideslope deviation command signal.


FIGURE 4-4 GLIDESLOPE DEVIATION SERVO LOOP

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FIGURE 4-6 GLIDESLOPE RETRACT CIRCUITRY


FIGURE 4-7 NAV FLAG CIRCUITRY

### 4.4 NAV FLAG CIRCUIT (Figure 4-7)

The NAV valid signal originating at the VOR/LOC receiver is connected to pins $K$ and $F$ of the upper P. C. board. Resistor R123 provides a 1 Kohm load to the receiver. This signal then passes through resistors R121 and R122 to differential amplifier 1102A. Negative feedback is provided by resistor R117 which also established a gain of ONE for the stage. Since the amplifier is powered by a single ended power supply, i.e., +28 VDC or $\pm 14 \mathrm{VDC}$ to ground, the summing junctions at pins 2 and 3 of 1102A must be biased positive with respect to ground in order for the op-amp to function. This bias voltage is developed across zener diode CR108 in series with resistor R114 when using +28VDC power, and in series with resistor R115 when using +14VDC power. This +5 . 1VDC bias voltage is connected to pin 3 of 1102A through resistor R118 and thus causes the output at pin 1 to stabilize at +5.1 VDC also.
The FLAG input voltage level from the NAV receiver will be inverted by 1102A and will appear at pin I in direct proportion to the input voltage change. From pin 1, the signal passes through resistor R116 to pin 6 of I102B. This signal is compared to the bias reference on pin 5 of I102B generated by zener diode CR108. During the NAV invalid condition the input voltage is near zero and the output from 1102A pin 1 is nearly 5. IVDC. The voltage at pin 5 of I102B, however, is less than 5. 1VDC because of the voltage divider consisting of resistors R112 and R113. This causes the voltage to + pin 7 of I102B to switch to ground potential, removing the drive to transistor Q104 and providing a small amount of positive feedback to pin 5 of I102B through resistors R110 and RI1I. When the input voltage increases to approximately +0.21 VDC , the output of I102A will decrease to +4 . 9VDC which is less than the reference voltage on pin 5 . This will cause amplifier 1102B to switch from near ground potential to +14VDC or +28VDC depending upon the power supply magnitude. Zener diode CR104 prevents transistor Q104 from turning on when 1102B is low since the output of this stage may be as high as one or two volts. When 1102B switches high, CR104 breaks down in the reverse direction, providing base current for Q104. This results in collector current through the NAV flag coil in series with CRI02 for 14VDC operation and R109 and CRIC1 for 28VDC operation. As the current builds up in the NAV flag coil, the small circular magnet between the coil poles rotates, causing the NAV flag to move up and out of view behind the front bezel.

### 4.5 POWER FLAG

The power flag operates in the same manner as the NAV flag, in that current flowing through the coil generates a magnetic field opposing the field in the circular magnet to which the flag is attached. This opposition causes the magnet to rotate and position the PWR flag out of view behind the front bezel. When the +15 V unregulated supply from the KG 102 gyro drops below 2. OVDC, the attraction of the circular magnet poles to the pole pieces becomes greater than the repulsion force of the coil generated field-and results in a rapid rotation of the circular magnet to align with the pole pieces. This results in the reappearance of the PWR flag from behind the upper bezel.

### 4.6 HEADING SELECT AND COURSE DATUM PICKOFF ASSEMBLIES

Dual photo detectors V102 and V103 (figure 4-8) provide the DC outputs that correspond to the heading select and course datum signals respectively. A light beam from LED CRI15 illuminates V102, and CR111 illuminates V103. These light beams are partially interrupted by a shutter that rides on the heading select, or course datum cam attached to the center yoke assembly. (Figure $4-8)$. The horizontal slit in the shutter allows a narrow beam of light to fall on the photocell. This light causes a decrease in resistance of the photocell elements, but if both segments are equally exposed as shown in Figure 4-8B, the output voltage when measured against the mid point of resistor combination R135 and R136, will be zero. Resistors R135 and R136 provide the reference point for both pickoffs and prevents power supply variations from affecting the output voltage.

As the heading bug or course pointer is rotated clockwise, the shutter moves upward in response to the increasing cam radius. This results in greater exposure of the upper half of the dual photocell as shown in Figure 4-8A. A reduction in the resistance of this half unbalances the voltage divider and produces a positive output voltage between the photocell center top and the junction of resistors R 135 and R 136. As the heading bug or course pointer is rotated counterclockwise, the shutter moves downward, exposing the bottom half of the photocell. (figure 4-8). This results in a negative output voltage between the photocell center top and the junction of resistors R 135 and R 136.
Rotation of the heading select bug will produce a continuously changing voltage within plus or minus 30 degrees of the upper lubber line. Beyond that point, the voltage will remain constant at approximately $\pm 12.5 \mathrm{VDC}$. When the bug is rotated to the bottom of the instrument, the voltage changes polarity and again remains constant until it is moved within 30 degrees of the upper lubber line where it begins to decrease toward zero volts.
The course datum cam is cut in a similar fashion, except that it is symmetrical on the upper and lower sections allowing for back course autopilot operation. In addition, the course cam has a larger linear range than the heading cam, extending out to 80 degrees on either side of the upper or lower lubber lines with only 20 degrees of constant radius on each side of the instrument.

### 4.7 NAV DEVIATION AND TO-FROM INDICATORS

Unlike the glideslope pointer, the NAV deviation and TO-FROM indicators are conventional meter movements mounted inside the center yoke assembly. The NAV meter is a 1000n, 15011a unit and the TO-FROM meter is a 200 n , 200pa device.
Drive current is supplied by the NAV receiver through P. C. board pins b and V for the NAV meter, and pins $Z$ and $T$ for the TO-FROM meter. From the P. C. board, the current passes through two pairs of brushes attached to the P. C. board that extended down on each side of four metal rings surrounding the.center yoke assembly as shown in Figure 4-9. Wires soldered to the four rings supply current to the respective meter movements.

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FIGURE 4-8 COURSE DATUM PICKOFF ASSEMBLY


FIGURE 4-9 CENTER YOKE WITH NAV AND TO-FROM BRUSH ASSEMBLY

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## SECTION V <br> MAINTENANCE

### 5.1 INTRODUCTION

This section deals with the testing, overhaul, and trouble shooting procedure for the KI 525 Pictorial Navigation Indicator.

### 5.2 TEST AND ALIGNMENT

### 5.2.1 GENERAL REQUIREMENTS

Unless otherwise specified all tests shall be conducted with the indicator in its normal operating position and at ambient room temperature ( $25 \pm 5$ degrees $C$ ) and humidity not to exceed $80 \%$.

### 5.2.1.1 ELECTRICAL

Output signals
a) HDG SEL $0.5 \quad \mathrm{vdc} / \mathrm{deg}$
b) CRS Datum $0.2 \quad \mathrm{vdc} / \mathrm{deg}$

Input signals
a) VOR deviation $15 \mathrm{mv} / \mathrm{deg}$
b) GS deviation $300 \mathrm{mv} / \mathrm{deg}$
c) VOR Flag valid 210 mv
d) GS Valid 210 mv
e) PWR Valid 15 vdc
f) TO-FROM $\pm 150 \mathrm{mv}$
g) Lighting $\pm 14 \quad \mathrm{vdc}$ or +28 vdc
h) Two phase state signal to stepper motor

### 5.2.1.2 MECHANICAL

a) Compass Card $1 / 4$ deg increments
b) HDG Sel Cam 0.0016 in/deg
c) CRS DTM Cam 0.0006 in/deg
5.2.2 TEST EQUIPMENT
a) KTS-153 Test Set
b) Precise angle indicator.
c) ORZ test circuit described in RTCA 209-54/DD-62
d) DC voltmeter-Similar to Fluke Model 8000A
e) Oscilloscope-Similar to Tektronix, Model 516.

### 5.2.3 CALIBRATION PROCEDURE

The initial phase of this procedure shall be performed with the unit in the final stage of assembly. The PC board shall be wired to the harness but not assembled to the main structural casting.

1) Place the KTS-153 Power Switch OFF. Connect the unit to the tester. Connect a precise angle indicator (PAI) to the HDG CX jacks on the front of the tester.
2) Carefully rotate the first gear forward of the slip rings until NORTH is precisely under the lubber line. Loosen the heading repeater hold-down screws, and rotate the synchro for $0.00^{\circ}$ on the PAI. Tighten the hold-down screws.
3) Rotate the heading card until EAST appears under the lubber line. The PAI shall read $90 \pm 1.0^{\circ}$.
4) Return the heading card to $0.0^{\circ}$, and loosen the slaving CT hold-down screws. Switch the PAI to the slaving CT, and rotate the synchro for $0.00^{\circ}$ on the PAI. Tighten the hold-down screws.
5) Rotate the heading card until EAST appears under the lubber line. The PAI shall read $90 \pm 1.0^{\circ}$.
6) Rotate the heading card to NORTH, and position the course pointer at $300^{\circ}$. Connect the ORZ test set to the OBS Resolver jacks. Loosen the course resolver holddown screws and calibrate the 30 Hz resolver according to the constant rotor voltage test procedures given in RTCA paper 209-54/DO-62. Tighten the hold-down screws. Assemble the PC board to the main structure but do not install the unit cover.
7) Place the following tester switches to the indicated position:

| SWITCH | POSITION |
| :--- | :--- |
| RES/DEV | DEV |
| D-BAR/TO-FM | D-BAR |
| METER | GS DEV |
| $14 / 28$ vdc | +14 vdc on Panel Meter |
| $\pm 15 \mathrm{vdc}$ | ON |
| +5 vdc | ON |
| GS DEV CMR | OFF |
| GS FLAG CMR | OFF |
| CCW-CW | CCW |
| Stepper Drive | OFF |
| NAV FLAG CMR | OFF |
| +15 VNREG | NORMAL |
| 115 VAC 400 Hz. | ON |

8) Adjust the $14 / 28 \mathrm{vdc}$ pot for 28 vdc on the tester voltmeter.
9) Place a black cloth over the indicator to remove as much light as possible from the three photocell areas. Adjust the GS flag pot fully clockwise, and the GS DEV pot for $0.0 \mathrm{vdc} \mathrm{E}(+)$ to $\mathrm{B}(-)(\mathrm{J} 2)$. Refer to figure $5-1$ and loosen the GS photocell assembly hold down screw. Carefully adjust the photocell assembly to position the glideslope pointer directly over the center mark on the glideslope scale when viewing the indicator from 25 degrees above the front. Tighten the photocell assembly holddown screw.
10) Adjust the GS DEV pot fully clockwise. The GS pointer shall move toward the top of the indicator. Adjust pot R147 until the GS pointer is just in view at the top of the indicator when viewed from $30^{\circ}$ above the longitudinal axis of the unit. Adjust the GS DEV pot for 0.0 Vdc .
11) Position the heading bug and the course pointer precisely under the lubber line. Loosen the two shutter hold-down screws on each shutter less than $1 / 2$ turn.
12) Monitor the voltage from $\mathrm{P}(+)$ to $\mathrm{S}(-)$ (J1). With the black cloth covering the unit, move the heading shutter (forward photocell) with the adjusting tool until the voltage $P(+)$ to $S(-)(\mathrm{J} 1)$ is 0.0 Vdc . Carefully tighten the two hold-down screws while maintaining 0.0 Vdc from $\mathrm{P}(+)$ to $\mathrm{S}(-)$.
13) Monitor the voltage from pin $\underline{e}(+)$ to $S(-)$ (J1). Repeat the above adjustment procedure on the CRS shutter (rearward).
14) Position the HDG bug to $10 \pm 0.5^{\circ}$ to the right of the lubber line and the CRS Pointer to $10 \pm 0.5^{\circ}$ to the left of the lubber line. Adjust R169 for +5.5 Vdc from pin $\mathrm{P}(+)$ to S(-) (J1) and adjust R170 for -2.1 vdc from pin e (+) to S(-) (J1).
15) Remove all power from the unit. Apply glyptal to the four shutter hold-down screws and to the GS photocell assembly hold-down screw. Place the cover on the unit, and secure it with two rear-mounted screws.

### 5.2.4 <br> FINAL TEST PROCEDURE

The unit shall be completely assembled with the cover in place.

1) Connect the unit to the tester, and set the panel switches as listed in 5.2 .3 (7) above. Place the heading and course pointers under the lubber line, and adjust the GS flag, GS deviation, and NAV flag sources for 0.0 Vdc. Record the following voltages:
a) $\quad \mathrm{J} 1 \mathrm{Pin} \mathrm{P}(+)$ to $\mathrm{S}(-) \quad 0.0 \pm 0.3 \mathrm{Vdc}$
b) $\quad \mathrm{J} 1 \mathrm{Pin} \underline{\mathrm{e}}(+)$ to $\mathrm{S}(-) \quad 0.0 \pm 0.60 \mathrm{Vdc}$
2) Adjust the $14 / 28 \mathrm{Vdc}$ pot for +11.2 Vdc on the panel meter. The NAV and PWR flags shall be fully in view. Slowly increase the NAV flag voltage until the NAV flag snaps up out of view. The flag shall be completely out of view.
NAV flag voltage $K(+)$ to $F(-) \quad+0.21 \pm 0.03 \mathrm{Vdc}$.
Adjust the 14/28 VDC pot for +14.0 Vdc .
3) Switch the NAV flag CMR switch to the POS position. Re-adjust the NAV flag voltage to the value recorded in 2 above. The NAV flag shall not be in view.
4) Switch the $14 / 28 \mathrm{~V}$ NAV PWR OFF. The NAV flag shall come completely into view.
5) Switch the $14 / 28$ V NAV PWR to the 28 V position, and adjust the $14 / 28$ VDC pot for +28.0 Vdc . The NAV flag shall go completely out of view.
6) Decrease the voltage to 22.4 Vdc . The NAV flag shall remain out of view.
7) Slowly decrease the NAV flag voltage until the NAV flag drops into view. The NAV flag voltage $\mathrm{K}(+)$ to $\mathrm{F}(-)$ shall be $0.17 \pm 0.03 \mathrm{Vdc}$. Return the input voltage to +28 Vdc .
8) Monitor the voltage on $\mathrm{P}(+)$ to $\mathrm{S}(-)$ and adjust the heading pointer $10^{\circ}$ left of the lubber line.
$\mathrm{P}(+)$ to $\mathrm{S}(-) \quad-5.5 \pm 1.2 \mathrm{Vdc}$
9) Continue to rotate the heading pointer to the left until the voltage stops changing. The pointer shall be $30 \pm 5^{\circ}$ right of the lubber line.
$\mathrm{P}(+)$ to $\mathrm{S}(-) \quad-12.5 \pm 2 \mathrm{Vdc}$
10) Adjust the pointer $10^{\circ}$ right of the lubber line.
$\mathrm{P}(+)$ to $\mathrm{S}(-) \quad+5.5 \pm 1.2 \mathrm{Vdc}$
(Offset recorded in 1)a) shall be used as the reference for this measurement.)
11) Continue to rotate the heading pointer to the right until the voltage stops changing. The pointer shall be $30 \pm 5^{\circ}$ right of the lubber line.

$$
\mathrm{P}(+) \text { to } \mathrm{S}(-) \quad+12.5 \pm 2 \mathrm{VVdc}
$$

12) Continue rotating the heading pointer to the right until the voltage switches to $-14 \pm 3 \mathrm{Vdc}$. The heading pointer shall be within $10^{\circ}$ of the bottom of the indicator.
13) Monitor the voltage $\mathrm{J} 1 \underline{\mathrm{e}}(+)$ to $\mathrm{S}(-)$, and adjust the course pointer $10^{\circ}$ left.
e(+) to S(-)
$-2.1 \pm 0.4 \mathrm{Vdc}$
14) Continue to rotate the course pointer to the left until the voltage stops changing. The pointer shall be $80 \pm 10^{\circ}$ left of the lubber line.

$$
\underline{e}(+) \text { to } S(-) \quad-12.5 \pm 2 \mathrm{Vdc}
$$

15) Adjust the course pointer $10^{\circ}$ right of the lubber line.
e(+) to S(-)
$+2.1 \pm 0.4 \mathrm{Vdc}$
16) Continue to rotate the course pointer to the right until the voltage stops changing. The pointer shall be $80 \pm 10$ degrees right of the lubber line.

$$
\underline{\mathrm{e}}(+) \text { to } \mathrm{S}(-) \quad+12.5 \pm 2 \mathrm{Vdc}
$$

17) Continue to rotate the course pointer to the right until the voltage begins to decrease.
CRS pointer $\quad 100 \pm 10$ deg. right of the lubber line
18) Continue the right hand rotation until the voltage reads 0.0 vdc. The course pointer shall be within 10 degrees of the bottom of the indicator.
19) Continue the right hand rotation until the voltage stops changing.

CRS pointer $\quad 100 \pm 10$ deg. left of the lubber line
20) Adjust the GS deviation for maximum positive, maximum negative, and then back to zero. At no time shall the GS pointer come into view.
21) Increase the GS flag voltage $\mathrm{J} 2-\mathrm{J}(+)$ to $\mathrm{J} 1-\mathrm{W}(-)$ to 0.215 Vdc .
a) The GS pointer shall drop into view within 10 seconds.
b) GS pointer center scale $\pm 1 / 2$ needle width (left side).
c) GS pointer center scale $\pm 1 / 2$ needle width (right side).
d) The GS pointer shall have no tendency to oscillate.
22) Switch the GS flag CMR switch to the POS, NEG, and then OFF positions. At no time shall the GS pointer move out of view.
23) Adjust the GS pointer to the following positions on the GS scale, and record the input voltages from E to B (J2).
$\begin{array}{ll}\text { a) One dot up } & +75 \pm 10 \mathrm{mVdc} \\ \text { c) } & \text { Two dots up }\end{array}$
d) Maximum up command

Pointer in view at top of scale when viewed at $30^{\circ}$ above unit centerline
e) One dot down
$-75 \pm 10 \mathrm{mVdc}$
f) Two dots down
$-150 \pm 20 \mathrm{mVdc}$
24) Adjust the GS flag voltage, (J2-J to J1-W), to 0.185 Vdc . The GS pointer shall slowly move up out of view.
25) Adjust the GS DEV voltage to 0.0 Vdc .
26) Place the RES/DEV switch to RES, and the DEV-BAR/TO-FROM switch to DEVBAR. Adjust the RES pot for 0.3 Vdc at TP-A.
(J1) Pin $\underline{b}$
$0.150 \pm 0.004 \mathrm{Vdc}$
27) Switch the DEV-BAR TO-FROM switch to the TO-FROM position, and adjust the RES pot for 0.3 Vdc at TP-A.
Pin Z
$0.050 \pm 0.005 \mathrm{Vdc}$
28) Switch the RES/DEV switch to DEV, and rotate the METER CURRENT adjust for a fully in-view TO indication. Position the course pointer under the lubber line.
(TO-FROM flag points toward course pointer.)
$\mathrm{J} 1 \mathrm{Z}(+)$ to $\mathrm{T}(-) \quad+200 \pm 40$ (adc
29) Repeat for a full FROM indication.

J1 Z(+) to T(-) $-200 \pm 40$ (adc
30) Rotate the Meter Current adjust to 0.0. Slowly rotate the course pointer $360^{\circ}$. The TO-FROM flag shall remain totally out of view when viewed from the front.
31) Tilt the unit $90^{\circ}$ up. The TO-FROM flag shall remain out of view.
32) Switch the DEV-BAR TO-FROM switch to the DEV-BAR position, and position the course pointer under the lubber line. With the Meter Current adjust at 0.0 Vdc , the course deviation bar shall be aligned with the ends of the course select pointer and the symbolic airplane centerline within $1 / 4$ bar width.
33) Slowly rotate the course pointer $360^{\circ}$. The DEV bar shall not move more than $1 / 2$ bar width.
34) Tilt the unit $90^{\circ}$ up. The DEV bar shall not move more than $1 / 2$ bar width.
35) Adjust the DEV bar to the following positions. Record the current readings on the panel Microamp Meter. The movement of the DEV bar shall be unrestricted throughout the travel.
a) One dot left $\quad-30 \pm 4$ (adc
b) Two dots left $-60 \pm 8$ (adc
c) Three dots left $-90 \pm 12$ (adc
d) Four dots left $-120 \pm 16$ (adc
e) Five dots left $-150 \pm 20$ (adc
f) Five dots right $+150 \pm 20$ (adc
g) Four dots right $+120 \pm 16$ (adc
h) Three dots right $+90 \pm 12$ (adc
i) Two dots right $+60 \pm 8$ (adc
j) One dot right $\quad+30 \pm 4$ (adc
36) Switch the stepper drive ON, and adjust the slew speed for a 1.0 -second square wave period at Pin A (J2). The heading card shall move smoothly with uniform steps. Switch the CW/CCW switch to CW, and check for smoothness.
37) Decrease the square wave period at Pin A (J2) to 67 ms , and check the display for smoothness in both directions.
38) Switch the stepper drive off, and position the heading bug to $360^{\circ}$, and the course pointer at $90^{\circ}$ relative to the compass card. Switch the stepper drive on, and allow the card to make two revolutions. The heading bug and the course pointer shall be within two degrees of the respective starting positions. Repeat this test with the display rotating in the opposite direction.
39) Rotate the heading knob in a direction opposite to that of the compass card. The compass card shall continue rotating smoothly without missing any steps. Repeat for the opposite direction. Allow the compass cards to rotate $360^{\circ}$ in each direction.
40) Decrease the square wave period at Pin A (J2) to 33 ms , and check the display for smoothness in both directions. There shall be no evidence of missed steps. Increase the square wave period to 0.1 second, and shut off the display.
41) Connect the PAI to the panel jacks shown, and position NORTH under the lubber line using the stepper drive direction and speed control.
a) PAI:
Slaving CT
$0.0 \pm 1.0^{\circ}$
b) PAI:
HDG CX
$0.0 \pm 1.0^{\circ}$

Position the compass card to the headings shown, and record the PAI values.

| c) | HDG: $90^{\circ}$ | Slave CT | $90 \pm 1.0^{\circ}$ |
| :--- | :--- | :--- | :--- |
|  |  | HDG CX | $90 \pm 1.0^{\circ}$ |
| d) | HDG: $180^{\circ}$ | Slave CT | $180 \pm 1.0^{\circ}$ |
|  |  | HDG CX | $180 \pm 1.0^{\circ}$ |
| e) | HDG: $270^{\circ}$ | Slave CT | $270 \pm 1.0^{\circ}$ |
|  |  | HDG CX | $270 \pm 1.0^{\circ}$ |
| f) | HDG: $0.0^{\circ}$ | Slave CT | $0 \pm 1.0^{\circ}$ |
|  |  | HDG CX | $0 \pm 1.0^{\circ}$ |

42) The course resolver shall be zeroed at $300^{\circ} \pm 1^{\circ}$ using the constant rotor voltage test in RTCA paper 209-54/DO-62.
43) The stator output voltages determined in accordance with the constant rotor voltage test shall be $0.180 \pm 0.012$.
44) Connect the resolver to a calibrated resolver, phase shifter, accuracy bridge, or equivalent error-measuring equipment, and excite the rotor with 0.5 V 30 Hz . Rotate the course knob clockwise to position the course pointer at $60^{\circ}$ increments from $0^{\circ}$ to $360^{\circ}$. The maximum error shall be $\pm 1^{\circ}$.
45) Switch the +15 unregulated switch to VARIABLE, and rotate the adjust pot fully counter-clockwise. The PWR flag shall be fully in view.
46) Slowly rotate the adjust pot clockwise until the PWR flag snaps out of view.

Pin $\underline{v}$ (J101) $\quad+10+3 /-4 \mathrm{Vdc}$
47) Slowly rotate the pot counter-clockwise until the PWR flag snaps into view.

Pin $\underline{v}$ (J101) $\quad+4 \pm 3 \mathrm{Vdc}$
48) Place the +15 unregulated switch to NORMAL.
49) Adjust the lighting pot fully CW and observe both lamps on and uniform illumination of the display.
50) Switch the $14 / 28 \mathrm{v}$ switch to 14 v and adjust for 14 vdc on the panel Meter. Both lamps shall be on and the display shall be illuminated in a uniform manner.
51) Slowly decrease the lighting intensity. The display illumination shall decrease in a smooth and uniform fashion.
52) Switch the $14 / 28 \mathrm{v}$ switch to 28 v and adjust for 28 vdc on the panel meter. Slowly increase the lighting intensity. The display illumination shall increase in a smooth and uniform manner.
53) Adjust the METER CURRENT pot for half-scale on the DEV-BAR, and slowly rotate the compass card $360^{\circ}$ using the stepper drive controls. There shall be no discontinuity in the DEV-BAR display.
54) Place the DEV-BAR/TO-FROM switch to TO-FROM, and adjust the METER CURRENT pot until the flag is just off the stop in either the TO or FROM position. Slowly rotate the compass card $360^{\circ}$. There shall be no discontinuity in the TO-FROM display.
55) Rotate the METER CURRENT pot fully clockwise. Reduce the current to 100 uadc. The TO-FROM flag shall move smoothly off the stop. Repeat for the opposite polarity.
56) Place the DEV-BAR/TO-FROM switch to the DEV-BAR position, and rotate the METER CURRENT pot fully clockwise. Rotate the compass card $360^{\circ}$. The D-bar shall not touch the compass card. Reduce the current to 90 uadc. The D-bar shall move smoothly off the stop. Repeat for the opposite polarity.

## THIS PAGE IS RESERVED

## TEST DATA SHEETS

1) $C R S$ AND HDG under lubber line
a) J 1 Pin P to $\mathrm{S}(-)$
$0.0+/-0.3 \mathrm{vdc}$
$0.0+/-0.6 \mathrm{vdc}$
2) Input voltage to 11.2 vdc NAV flag out of view J1K to P(-)
3) NAV flag CMR to Pos

NAV flag
4) $14 / 28$ vdc OFF NAV flag
5) $28 v$ input power NAV flag
6) Input voltage to 22.4 vdc

NAV flag
7) NAV threshold

NAV flag in view
J1K to F(-)
PWR VALID
PWR flag
8) HDG SEL 10 deg Left

J1P to S(-)
9) HDG SEL to limit left J1P to S(-)
10) HDG SEL 10 deg Right J1P to S(-)
11) HDG SEL to limit Right J1P to S(-)
12) HDG SEL Right to Crossover
13) CRS 10 deg Left J1e to S(-)
14) CRS to limit left J1e to S(-)
15) CRS 10 deg Right J1e to S(-)
16) CRS to limit Right J1e to S(-)
17) End of CRS limit Right
18) CRS Null at bottom
19) End of CRS limit left
20) GS Max Pos, Neg, Zero
$\qquad$ $0.21+/-0.03$ vdc
$\qquad$ out of view
$\qquad$ IN VIEW
$\qquad$
out of view
$\qquad$

| 0.17+/-0.03vdc |
| :---: |
| Out of view |
| $5.5+/-1.2 \mathrm{vdc}$ |

$\ldots-12.5+/-2 \mathrm{vdc}$
$\ldots+5.5+/-1.2 \mathrm{vdc}$
_ $30+/-5$ deg Right
$\ldots+12.5+/-2 \mathrm{vdc}$
_ bottom +/-10 deg
$\qquad$ $-2.1+/-0.4 \mathrm{vdc}$
$\qquad$ $-2.1+/-0.4 \mathrm{vdc}$ 12.5 +/-2 vdc
$\qquad$ +2.1 +/-0.4vdc
$\qquad$ $80+/-10$ deg Right
$\qquad$ $+12.5+/-2 \mathrm{vdc}$
$\qquad$ $100+/-10$ deg Right
$\qquad$ bottom +/-10 deg
$\qquad$ $100+/-10$ deg left
$\qquad$ Out of view
21) GS Flag to J2-J to JI-W(-)
a) GS Pointer
b) GS Left Pointer
c) GS Right Pointer
d) GS Pointer
22) GS CMR - Pos, Neg, OFF
23) GS Scale - J2E to B(-)
a) One dot up
b) two dots up
c) Max up
d) One dot down
e) Two dots down
24) GS Flag J2 - J to J1 - W

GS Pointer
25) RES pot for $0.3 v d c$ (D-BAR) J1- $\underline{b}$
26) Res Pot for 0.3vdc (TO-FM) J1-Z
27) Full TO indication

J1-Z to T(-)
28) Full FROM Indication

JI-Z to T(-)
29) TO-FM to Zero

Rotate CRS
TO-FM
30) Unit 90 degrees UP

TO-FM
31) Align D-BAR and CRS Pointer
32) Rotate CRS

D-BAR
33) UNIT 90 degrees UP

D-BAR
34) D-BAR Scale
a) One dot left
b) Two dots left
c) Three dots left
d) Four dots left
e) Five dots left
f) Five dots right
g) Four dots right
h) Three dots right
i) Two dots right
j) One dot right
35) Pin A Period - 1.0 sec

Clockwise Motion
Counter Clockwise Motion
36) Pin A Period - 67 ms

CW Motion $\qquad$
37) HDG bug at 360 degrees

CRS at 90 degrees
Two Revolutions
HDG bug
CRS
Reverse Direction
HDG bug
CRS
38) HDG bug opposite of Card

Compass Card
Opposite direction
Compass Card
39) Pin A period - 33 Ms .

Compass Card
Pin A period 0.1 second DISPLAY OFF
40) PAI check - N under lubber line
a) Slaving CT
b) HDG CX

## - <br> $0.0+/-1.0 \mathrm{deg}$ <br> $\longrightarrow 0.0+/-1.0 \mathrm{deg}$

Compass Check
a) HDG - 90 deg

Slave CT
HDG CX
b) HDG-180 deg

Salve CT
HDG CX
c) HDG - 270 deg .

Slave CT
HDG CX
d) HDG -0.0 deg

Slave CT
HDG CX
41) CRS Resolver
42) Stator Output Voltage
43) CRS Resolver Accuracy

CRS - 0.0 deg
60 deg
120 deg 180 deg 240 deg 300 deg
44) 15 volt unreg fully CCW PWR Flag
45) PWR Flag out of view JI-Pin $\underline{v}$
$90+/-1.0 \mathrm{deg}$
$90+/-1.0 \mathrm{deg}$
$\ldots \begin{aligned} & 180+/-1.0 \mathrm{deg} \\ & 180+/-1.0 \mathrm{deg}\end{aligned}$
$270+/-1.0 \mathrm{deg}$
$270+/-1.0 \mathrm{deg}$
$\square$
$0.0+/-1.0$ deg $0.0+/-1.0 \mathrm{deg}$
$\ldots$ OK
$\ldots 0.180+/-0.012$ VAC
_ $0.0+/-1 \mathrm{deg}$
$60+/-1$ deg $120+/-1$ deg $180+/-1$ deg $240+/-1$ deg 300 +/-1 deg
$\qquad$ IN VIEW
$\qquad$ $+10+3 /-4 \mathrm{vdc}$

| 46) PWR Flag in view JI-Pin $\underline{v}$ | +4 +/-3vdc |
| :---: | :---: |
| 47) PWR INVALID PWR Flag | IN VIEW |
| 48) Lighting | OK |
| 49) Lighting to $14 v$ | OK |
| 50) Variable Lighting Intensity | OK |
| 51) Lighting to 28 V | OK |
| 52) D-BAR Continuity | OK |
| 53) TO-FM Continuity | OK |
| 54) TO-FM Stops Opposite polarity | $\begin{aligned} & \mathrm{OK} \\ & \mathrm{OK} \end{aligned}$ |
| 55) D-BAR Interference D-BAR Stops Opposite polarity | $\begin{aligned} & \mathrm{OK} \\ & \mathrm{OK} \\ & \mathrm{OK} \end{aligned}$ |



FIGURE 5-1 Glideslope Assembly Calibration

## THIS PAGE IS RESERVED

### 5.3 OVERHAUL

### 5.3.1 VISUAL INSPECTION

This section contains instructions and information to assist in determining, by visual inspection, the condition of the units major assemblies and subassemblies. These inspection procedures will assist in finding defects resulting from wear, physical damage, deterioration, or other causes. To aid inspection, detailed procedures are arranged in alphabetical order.
A. Capacitors, Fixed

Inspect capacitors for case damage, body damage, and cracked, broken, or charred insulation. Check for loose, broken, or corroded terminal studs, lugs, or leads. Inspect for loose, broken, or improperly soldered connections. On chip caps, be especially alert for hairline cracks in the body and broken terminations.
B. Capacitors, Variable

Inspect trimmers for chipped and cracked bodies, damaged dielectrics, and damaged contacts.
C. Chassis

Inspect the chassis for loose or missing mounting hardware, deformation, dents, damaged fasteners, or damaged connectors. In addition, check for corrosion or damage to the finish that should be repaired.
D. Circuit Boards

Inspect for loose, broken, or corroded terminal connections; insufficient solder or improper bonding; fungus, mold, or other deposits; and damage such as cracks, burns, or charred traces.
E. Connectors

Inspect the connector bodies for broken parts; check the insulation for cracks, and check the contacts for damage, misalignment, corrosion, or bad plating. Check for broken, loose, or poorly soldered connections to terminals of the connectors. Inspect connector hoods and cable clamps for crimped wires.
F. Covers and Shields

Inspect covers and shields for punctures, deep dents, and badly worn surfaces. Also, check for damaged fastener devices, corrosion and damage to finish.
G. Flex Circuits

Inspect flex circuits for punctures, and badly worn surfaces. Check for broken traces, especially near the solder contact points.
H. Front Panel

Check that name, serial, and any plates or stickers are secure and hardware is tight. Check that the handle is functional, securely fastened, and handle casting is not damaged or bent.
I. Fuse

Inspect for blown fuse and check for loose solder joints.
J. Insulators

Inspect insulators for evidence of damage, such as broken or chipped edges, burned areas, and presence of foreign matter.
K. Jacks

Inspect all jacks for corrosion, rust, deformations, loose or broken parts, cracked insulation, bad contacts, or other irregularities.
L. Potentiometers

Inspect all potentiometers for evidence of damage or loose terminals, cracked insulation or other irregularities.
M. Resistors, Fixed

Inspect the fixed resistors for cracked, broken, blistered, or charred bodies and loose, broken, or improperly soldered connections. On chip resistors, be especially alert for hairline cracks in the body and broken terminations.
N. RF Coils

Inspect all RF coils for broken leads, loose mountings, and loose, improperly soldered, or broken terminal connections. Check for crushed, scratched, cut or charred windings. Inspect the windings, leads, terminals and connections for corrosion or physical damage. Check for physical damage to forms and tuning slug adjustment screws.
O. Terminal Connections Soldered
(1) Inspect for cold-soldered or resin joints. These joints present a porous or dull, rough appearance. Check for strength of bond using the points of a tool.
(2) Examine the terminals for excess solder, protrusions from the joint, pieces adhering to adjacent insulation, and particles lodged between joints, conductors, or other components.
(3) Inspect for insufficient solder and unsoldered strands of wire protruding from the conductor at the terminal. Check for insulation that is stripped back too far from the terminal.
(4) Inspect for corrosion at the terminal.
P. Transformers
(1) Inspect for signs of excessive heating, physical damage to the case, cracked or broken insulation, and other abnormal conditions.
(2) Inspect for corroded, poorly soldered, or loose connecting leads or terminals.
Q. Wiring/Coaxial Cable

Inspect wiring in chassis for breaks in insulation, conductor breaks, cut or broken lacing and improper dress in relation to adjacent wiring or chassis.
5.3.2 CLEANING
A. General

This section contains information to aid in the cleaning of the component parts and subassemblies of the unit.

WARNING:
GOGGLES ARE TO BE WORN WHEN USING PRESSURIZED AIR TO BLOW DUST AND DIRT FROM EQUIPMENT. ALL PERSONNEL SHOULD BE WARNED AWAY FROM THE IMMEDIATE AREA.

WARNING:
OPERATIONS INVOLVING THE USE OF A CLEANING SOLVENT SHOULD BE PERFORMED UNDER A VENTILATED HOOD. AVOID BREATHING SOLVENT VAPOR AND FUMES; AVOID CONTINUOUS CONTACT WITH THE SOLVENT. WEAR A SUITABLE MASK, GOGGLES, GLOVES, AND AN APRON WHEN NECESSARY. CHANGE CLOTHING UPON WHICH SOLVENTS HAVE BEEN SPILLED.

## WARNING:

OBSERVE ALL FIRE PRECAUTIONS FOR FLAMMABLE MATERIALS. USE FLAMMABLE MATERIALS IN A HOOD PROVIDED WITH SPARK-PROOF ELECTRICAL EQUIPMENT AND AN EXHAUST FAN WITH SPARKPROOF BLADES.
B. Recommended Cleaning Agents

Table 5-1 lists the recommended cleaning agents to be used during overhaul of the unit.

NOTE:
EQUIVALENT SUBSTITUTES MAY BE USED FOR LISTED CLEANING AGENTS.

| TYPE | USED TO CLEAN |
| :--- | :--- |
| Denatured Alcohol | Various, exterior and interior |
| DuPont Vertrel SMT | Various, interior |
| PolaClear Cleaner (Polaroid Corp.) or <br> Texwipe TX129 (Texwipe Co.) | CRT display filter, LCD displays, and <br> general purpose lens/glass cleaner. |
| KimWipes lint-free tissue <br> (Kimberly Clark Corp.) | Various |
| Cloth, lint-free cotton | Various |
| Brush, flat with fiber bristles | Various |
| Brush, round with fiber bristles | Various |
| Dishwashing liquid (mild) | Nylon, Rubber Grommets |

TABLE 5-1 RECOMMENDED CLEANING AGENTS
C. Recommended Cleaning Procedures

## CAUTION:

DO NOT ALLOW SOLVENT TO RUN INTO SLEEVES OR CONDUIT THAT COVERS WIRES CONNECTED TO INSERT TERMINALS.

1. Exterior
(a) Wipe dust cover and front panel with a lint-free cloth dampened with denatured alcohol.
(b) For cleaning connectors, use the following procedure.
(1) Wipe dust and dirt from bodies, shells, and cable clamps using a lint-free cloth moistened with denatured alcohol.
(2) Wipe parts dry with a clean, dry lint-free cloth.
(3) Remove dirt and lubricant from connector inserts, insulation, and terminals using a small soft bristled brush moistened with denatured alcohol.
(4) Dry the inserts with an air jet.
(c) Remove cover(s).
(d) If necessary, open any blocked ventilation holes by first saturating the debris clogging the apertures with denatured alcohol and then blowing the loosened material out with an air stream.
2. Interior

The following solvents are no longer recommended for benchtop or rework cleaning of printed circuit boards, modules, or sub-assemblies.

| FREON TF, IMC | TRICHLOROETHANE |
| :--- | :--- |
| CARBON TETRACHLORIDE | DETERGENT (ALL™ AND EQUIVALENTS) |
| CHLOROFORM | METHYLENE CHLORIDE |
| TRICHLOROETHYLENE | GENESOLV 2004/2010 |
| PROPYL ALCOHOL | METHYL ALCOHOL |
| ETHYL ALCOHOL | BUTYL ALCOHOL |
| XYLENE | PRELETE (CFC-113) |

TABLE 5-2 UNSAFE CLEANING AGENTS

CAUTION:
DO NOT USE SOLVENT TO CLEAN PARTS COMPOSED OF OR CONTAINING NYLON OR RUBBER GROMMETS. CLEAN THESE ITEMS WITH MILD LIQUID DISHWASHING DETERGENT AND WATER. USE DETERGENT FOR THIS PURPOSE ONLY.

CAUTION:
DUPONT VERTREL SMT DOES HAVE GENERAL MATERIAL COMPATIBILITY PROBLEMS WITH POLYCARBONATE, POLYSTYRENE, AND RUBBER. IT IS RECOMMENDED THAT THESE MATERIALS BE CLEANED WITH DENATURED ALCOHOL.

CAUTION:
DO NOT ALLOW EXCESS CLEANING SOLVENT TO ACCUMULATE IN ANY OF THE ADJUSTMENT SCREW CREVICES AND THEREBY SOFTEN OR DISSOLVE THE ADJUSTMENT SCREW EPOXY SEALANT.

CAUTION:
AVOID AIR-BLASTING SMALL TUNING COILS AND OTHER DELICATE PARTS BY HOLDING THE AIR NOZZLE TOO CLOSE. USE BRUSHES CAREFULLY ON DELICATE PARTS.

CAUTION:
IMPROPER CLEANING CAN RESULT IN SURFACE LEAKAGE AND CONDUCTIVE PARTICULATES, SUCH AS SOLDER BALLS OR METALLIC CHIPS, WHICH CAN CAUSE ELECTRICAL SHORTS. SEVERE IONIC CONTAMINATION FROM HANDLING AND FROM ENVIRONMENTAL CONDITIONS CAN RESULT IN HIGH RESISTANCE OR OPEN CIRCUITS.

CAUTION:
ULTRASONIC CLEANING CAN DAMAGE CERTAIN PARTS AND SHOULD GENERALLY BE AVOIDED.

NOTE:
Solvents may be physically applied in several ways including agitation, spraying, brushing, and vapor degreasing. The cleaning solvents and methods used shall have no deleterious effect on the parts, connections, and materials being used. If sensitive components are being used, spray is recommended. Uniformity of solvent spray flow should be maximized and wait-time between soldering and cleaning should be minimized.

NOTE:
Clean each module subassembly. Then remove any foreign matter from the casting.

Remove each module subassembly. Then remove any foreign matter from the casting.
(a) Casting covers and shields should be cleaned as follows:
(1) Remove surface grease with a lint-free cloth.
(2) Blow dust from surfaces, holes, and recesses using an air stream.
(3) If necessary, use a solvent, and scrub until clean, working over all surfaces and into all holes and recesses with a suitable non-metallic brush.
(4) Position the part to dry so the solvent is not trapped in holes or recesses. Use an air stream to blow out any trapped solvent.
(5) When thoroughly clean, touch up any minor damage to the finish.
(b) Assemblies containing resistors, capacitors, rf coils, inductors, transformers, and other wired parts should be cleaned as follows:
(1) Remove dust and dirt from all surfaces, including all parts and wiring, using soft-bristled brushes in conjunction with air stream.
(2) Any dirt that cannot be removed in this way should be removed with a brush (not synthetic) saturated with an approved solvent, such as mentioned above. Use of a clean, dry air stream ( 25 to 28 psi ) is recommended to remove any excess solvent.
(3) Remove flux residue, metallic chips, and/or solder balls with an approved solvent.
(c) Wired chassic devices containing terminal boards, resistor and capacitor assemblies, rf coils, switches, sockets, inductors, transformers, and other wired parts should be cleaned as follows:

NOTE:
When necessary to disturb the dress of wires and cables, note the positions before disturbing and restore them to proper dress after cleaning.
(1) Blow dust from surfaces, holes, and recesses using an air jet.
(2) Finish cleaning chassis by wiping finished surfaces with a lint-free cloth moistened with solvent.
(3) Dry with a clean, dry, lint-free cloth.
(4) When thoroughly clean, touch-up any minor damage to the finish.
(5) Protect the chassis from dust, moisture, and damage pending inspection.
(d) Ceramic and plastic parts should be cleaned as follows:
(1) Blow dust from surfaces, holes, and recesses using an air jet.
(2) Finish cleaning chassis by wiping finished surfaces with a lint-free cloth moistened with solvents.
(3) Dry with a clean, dry, lint-free cloth.

### 5.3.3 REPAIR

A. General

This section contains information required to perform limited repairs on the unit.
The repair or replacement of damaged parts in airborne electronic equipment usually involves standard service techniques. In most cases, examination of drawings and equipment reveals several approaches to perform a repair. However, certain repairs demand following an exact repair sequence to ensure proper operation of the equipment. After correcting a malfunction in any section of the unit, it is recommended that a repetition of the functional test of the unit be performed.
B. Repair Precautions

1. Ensure that all ESDS and MOS handling precautions are followed.
2. Perform repairs and replace components with power disconnected from equipment.
3. Use a conductive table top for repairs and connect table to ground conductors of 60 Hz and 400 Hz power lines.
4. Replace connectors, coaxial cables, shield conductors, and twisted pairs only with identical items.
5. Reference "component side" of a printed circuit board in this manual means the side on which components are located; "solder side" refers to the other side. The standard references are as follows: nearside is the component side; farside is the solder side; on surface mount boards with components on both sides, the nearside is the side that has the J\#\#\#\# and P\#\#\#\# connector numbers.
6. When repairing circuits, carefully observe lead dress and component orientation. Keep leads as short as possible and observe correct repair techniques.
7. There are certain soldering considerations with surface mount components. The soldering iron tip should not touch the ceramic component body. The iron should be applied only to the termination-solder filet.
8. Observe cable routing throughout instrument assembly, prior to disassembly, to enable a proper reinstallation of cabling during reassembly procedures.

## CAUTION

THIS EQUIPMENT CONTAINS ELECTROSTATIC DISCHARGE SENSITIVE (ESDS) DEVICES. EQUIPMENT MODULES AND ESDS DEVICES MUST BE HANDLED IN ACCORDANCE WITH SPECIAL ESDS HANDLING PROCEDURES.
C. Electrostatic Sensitive Devices (ESDS) Protection

1. Always discharge static before handling devices by touching something that is grounded.
2. Use a wrist strap grounded through a $1 \mathrm{M} \Omega$ resistor.
3. Do not slide anything on the bench. Pick it up and set it down instead.
4. Keep all parts in protective cartons until ready to insert into the board.
5. Never touch the device leads or the circuit paths during assembly.
6. Use a grounded tip, low wattage soldering station.
7. Keep the humidity in the work environment as high as feasibly possible.
8. Use grounded mats on the work station unless table tops are made of approved antistatic material.
9. Do not use synthetic carpet on the floor of the shop. If a shop is carpeted, ensure that a grounded mat is placed at each workstation.
10. Keep common plastics out of the work area.
D. MOS Device Protection

MOS (Metal Oxide Semiconductor) devices are used in this equipment. While the attributes of MOS type devices are many, characteristics make them susceptible to damage by electrostatic or high voltage charges. Therefore, special precautions must be taken during repair procedures to prevent damaging the device. The following precautions are recommended for MOS circuits, and are especially important in low humidity or dry conditions.

1. Store and transport all MOS devices in conductive material so that all exposed leads are shorted together. Do not insert MOS devices into conventional plastic "snow" or plastic trays used for storing and transporting standard semiconductor devices.
2. Ground working surfaces on workbench to protect the MOS devices.
3. Wear cotton gloves or a conductive wrist strap in series with a $200 \mathrm{~K} \Omega$ resistor connected to ground.
4. Do not wear nylon clothing while handling MOS devices.
5. Do not insert or remove MOS devices with power applied. Check all power supplies to be used for testing MOS devices. and be sure that there are no voltage transients present.
6. When straightening MOS leads, provide ground straps for the apparatus for the device.
7. Ground the soldering iron when soldering a device.
8. When possible, handle all MOS devices by package or case, and not by leads. Prior to touching the device, touch an electrical ground to displace any accumulated static charge. The package and substrate may be electrically common. If so, an electrical discharge to the case would cause the same damage as touching the leads.
9. Clamping or holding fixtures used during repair should be grounded, as should the circuit board, during repair.
10. Devices should be inserted into the printed circuit boards such that leads on the back side do not contact any material other than the printed circuit board (in particular, do not use any plastic foam as a backing).
11. Devices should be soldered as soon as possible after assembly. All soldering irons must be grounded.
12. Boards should not be handled in the area around devices, but rather by board edges.
13. Assembled boards must not be placed in conventional, home-type, plastic bags. Paper bags or antistatic bags should be used.
14. Before removing devices from conductive portion of the device carrier, make certain conductive portion of carrier is brought in contact with well grounded table top.
E. PC Board, Two-Lead Component Removal (Resistors, Capacitors, Diodes, etc.)
15. Heat one lead from component side of board until solder flows, and lift one lead from board; repeat for other lead and remove component (note orientation).
16. Melt solder in each hole, and using a desoldering tool, remove solder from each hole.
17. Dress and form leads of replacement component; insert leads into correct holes.
18. Insert replacement component observing correct orientation.
F. PC Board, Multi-Lead Component Removal (IC's, etc.)
19. Remove component by clipping each lead along both sides. Clip off leads as close to component as possible. Discard component.
20. Heat hole from solder side and remove clipped lead from each hole.
21. Melt solder in each hole, and using a desoldering tool, remove solder from each hole.
22. Insert replacement component observing correct orientation.
23. Solder component in place from farside of board. Avoid solder runs. No solder is required on contacts where no traces exist.
G. Replacement of Power Transistors
24. Unsolder leads and remove attaching hardware. Remove transistor and hard-coat insulator.
25. Apply Thermal Joint Compound Type 120 (Wakefield Engineering, Inc.) to the mounting surface of the replacement transistor.
26. Reinstall the transistor insulator and the power transistor using hardware removed in step (1).
27. After installing the replacement transistor, but before making any electrical connections, measure the resistance between the case of the transistor and the chassis, to ensure that the insulation is effective. The resistance measured should be greater than $10 \mathrm{M} \Omega$.
28. Reconnect leads to transistor and solder in place.
H. Replacement of Printed Circuit Board Protective Coating

WARNING
CONFORMAL COATING CONTAINS TOXIC VAPORS! USE ONLY WITH ADEQUATE VENTILATION.

1. Clean repaired area of printed circuit board per instructions in the Cleaning section of this manual.
2. Apply Conformal Coating, Humiseal \#1B-31 HYSOL PC20-35M-01 (Humiseal Division, Columbia Chase Corp., 24-60 Brooklyn Queens Expressway West, Woodside, N.Y., 11377) P/N 016-01040-0000.
3. Shake container well before using.
4. Spray or brush surfaces with smooth, even strikes. If spraying, hold nozzle 10-15 inches from work surface.
5. Cure time is ten minutes at room temperature.
I. Programmable Read Only Memory (PROM) Replacement

The read only memory packages are specially programmed devices to provide specific logic outputs required for operation in the unit. The manufacturer's part (type) number is for the un-programmed device, and cannot be used. The Honeywell part number must be used to obtain the correctly programmed device. Refer to the "lllustrated Parts List" (IPL).

### 5.3.3.1 REPLACEMENT OF COMPONENTS

This section describes the procedure, along with any special techniques, for replacing damaged or defective components.
A. Connectors

When replacing a connector, refer to the appropriate PC board assembly drawing, and follow the notes, to ensure correct mounting and mating of each connector.
B. Crystal

The use of any crystal, other than a Honeywell crystal, is considered an unauthorized modification.
C. Diodes

Diodes used are silicon and germanium. Use long-nose pliers as a heat sink, under normal soldering conditions. Note the diode polarity before removal.
D. Integrated Circuits

Refer to the applicable reference for removal and replacement instructions.
E. Wiring/Coaxial Cable

When repairing a wire that has broken from its terminal, remove all old solder, and pieces of wire from the terminal, re-strip the wire to the necessary length, and resolder the wire to the terminal. Replace a damaged wire or coaxial cable with one of the same type, size and length.

### 5.3.4

NOTE:
Instrument and gyro repair must be accomplished by a Honeywell approved Instrument service center, Warranty is valid only when the dust cover seal is intact.

The following instructions include the procedures that are necessary to remove and disassemble the subassemblies of the KI 525.

It is assumed that the dust cover has been removed and the unit has been tested according to the test procedures provided in paragraph 5.2 to locate the source of the malfunction. The unit should then be disassembled only to the station where the malfunction can be corrected by repair, cleaning, or adjustment. Do not disassemble any parts or wiring unnecessarily as repeated tear downs can be detrimental to the life of the unit.
The KI 525 is made up of eleven major subassemblies and a final assembly, The final assembly contains the necessary components and hardware required to bring the subassemblies together into a functional unit.
Disassembly instructions are provided to separate the subassembly from the basic unit, however, detailed breakdown of the components on each subassembly has not been included as this can be accomplished by referring to subassembly drawing (see Section VI). Reassembly can be accomplished by reversing the disassembly procedure. Special notes and adjustments are included in paragraph 5.3.3.7.

WARNING
REMOVE ALL POWER FROM THE UNIT BEFORE DISASSEMBLY OF ANY MODULE. BESIDES BEING DANGEROUS TO LIFE, VOLTAGE TRANSIENTS CAN CAUSE CONSIDERABLE DAMAGE TO THE EQUIPMENT.

# CAUTION <br> EXERCISE EXTREME CARE WHEN DISCONNECTING AND RECONNECTING MULTIPLE PIN CONNECTORS, TO ENSURE THAT THE CONNECTORS ARE NOT DAMAGED BY MISALIGNMENT OF THE PINS. 

CAUTION
THIS EQUIPMENT CONTAINS ELECTROSTATIC DISCHARGE SENSITIVE (ESDS) DEVICES. EQUIPMENT, MODULES, AND ESDS DEVICES MUST BE HANDLED IN ACCORDANCE WITH SPECIAL ESDS HANDLING PROCEDURES.

### 5.3.4.1 BEZEL REMOVAL

A. Loosen the two set screws in the "HDG" and "CRS" knobs and remove the knobs.
B. The bezel assembly is held to the front display assembly by four screws. Removal of these four screws allows the bezel assembly to slide forward off of the knob shafts. Exercise caution when handling the lighting components as these parts are easily scratched.
5.3.4.2 P.C. BOARD REMOVAL
A. Remove four screws that hold the P. C. board to the front display assembly.
B. Remove the two keying pins from the connector at the back of the P. C. board. Note the location of these two keying pins and replace them in their original location.
C. The board may now be rotated towards the left-hand side of the unit.
D. If further removal of the board is required, tag and unsolder all wires from the board.
5.3.4.3

REAR PLATE REMOVAL
A. Remove the two keying pins from both connectors that are fastened to the rear plates. Note the relative location of these four keying pins and replace them in their original location.
B. Remove two screws that fasten the rear plate to the glideslope plate.
C. Remove the one screw that holds the rear plate to the synchro gear plate.
D. Spring the glideslope arm over the pivot pin on the right-hand side of the rear plate. Exercise caution when removing the glideslope arm and bend the arm only the required amount to lift it off of the pivot pin.
E. The rear plate assembly may now be removed from the unit.

### 5.3.4.4 GLIDESLOPE PLATE REMOVAL

A. Remove the rear plate as outlined in Section 5.3.3.3.
B. Remove one screw and remove the photo detector housing from the glideslope plate.
C. Mark the top of the shaft and the hub of the glideslope arm to indicate relative rotational alignment of the two parts.
D. Loosen the two set screws in the hub of the glideslope arm and remove the glideslope arm from the unit. Exercise caution when removing the glideslope arm to prevent over bending of the part,
E. Remove the two screws between the synchro plate and the glideslope plate and remove the glideslope plate from the unit.
F. If complete freedom from the main unit is desired of the glideslope plate then tag and unsolder the seven wires between the glideslope plate and the P. C. board.
5.3.4.5 SYNCHRO PLATE REMOVAL
A. Remove the rear plate and glideslope plate as outlined in paragraphs 5.3.3.3 and 5.3.3.4.
B. Press the 029-00255-0000 36-tooth gear off the back of the drive shaft.
C. Remove the two screws that hold the P. C. board to the synchro plate.
D. Remove the four screws that hold the synchro plate to the front frame and remove the synchro plate from the unit.

### 5.3.4.6 FRONT FRAME AND YOKE REMOVAL

A. Remove the bezel and P. C. board assemblies as outlined in paragraphs 5.3.3.1 and 5.3.3.2.
B. Remove the four screws that hold the front frame to the synchro plate, spread the glideslope arms slightly, and then slide the front frame forward approximately $1 / 2$ inch.
C. Press the 029-00255-0000 36-tooth gear off the back of the drive shaft.
D. While manually supporting the yoke assembly slide both the front frame and yoke assemblies forward until they are free of the main unit.
E. The yoke assembly is held captive in the front frame assembly by the course pointer and tail. The course pointer and tail are glued to the NAV mask. To separate the yoke assembly from the front frame, remove the course pointer and tail, then slide the yoke assembly back from the front frame.
5.3.4.7 SPECIAL REASSEMBLY INSTRUCTIONS
A. When reassemblying any subassembly, refer to the assembly drawing (Section VI), and adhere to all of the notes and instructions on that drawing.
B. In general there should be at least . 015 inches clearance between moving components and other objects within the unit.
C. Make certain that the four brushes are properly aligned and making electrical contact with the four slip rings on the yoke assembly.
D. Any parts that are held together with adhesive must be cleaned prior to applying any adhesive.
E. When the yoke assembly is positioned, it must not be located such that it compresses the clutch wave washer between the heading select and heading gears.
F. The lighting components within the bezel should be handled by the edges of these parts only.
If cleaning is necessary, luke warm water and mild soap may be used. Rinse thoroughly and dry with a soft lint free cloth. Do not wipe any more than necessary as these parts are easily scratched.
G. After the P. C. board has been installed, check the shutter of both the course and heading select pickoffs to insure that they are riding in their proper cam locations.
H. Realign the resolver, synchros, and optical pickoffs per the instructions given in Section 5.2.

### 5.4 TROUBLESHOOTING

The troubleshooting diagram, refer to figure 5-2, is intended as a guide for the technician in isolating a malfunction of the unit. Before troubleshooting the unit, a thorough understanding of the Theory of Operation should be accomplished. The technique of fault finding through elimination should be used as a basis in locating the trouble area.
Before any troubleshooting procedures are applied, perform a bench check to determine if the unit is the source of the problem. If it is, determine in which assembly the problem lies. Once the problem section has been determined, consult the troubleshooting flowchart and schematics for information pertaining to repair.


## ILLUSTRATED PARTS LIST

### 6.1 General

The Illustrated Parts List (IPL) is a complete list of assemblies and parts required for the unit. The IPL also provides for the proper identification of replacement parts. Individual parts lists within this IPL are arranged in numerical sequence starting with the top assembly and continuing with the sub-assemblies. All mechanical parts will be separated from the electrical parts used on the sub-assembly. Each parts list is followed by a component location drawing.

Parts identified in this IPL by Honeywell part number meet design specifications for this equipment and are the recommended replacement parts. Warranty information concerning Honeywell replacement parts is contained in Service Memo \#1, P/N 600-08001-00XX.

Some part numbers may not be currently available. Consult the current Honeywell catalog or contact a Honeywell representative for equipment availability.

### 6.2 Revision Service

The manual will be revised as necessary to reflect current information.
6.3 List of Abbreviations

| Abbreviation | Name |
| :--- | :--- |
| B | Motor or Synchro |
| C | Capacitor |
| CJ | Circuit Jumper |
| CR | Diode |
| DS | Lamp |
| E | Voltage or Signal Connect Point |
| FL | Fuse |
| FT | Filter |
| I | Feedthru |
| J | Integrated Circuit |
| L | Jack or Fixed Connector |
| M | Inductor |
| P | Meter |

Table 1
Abbreviations

| Abbreviation | Name |
| :--- | :--- |
| Q | Transistor |
| R | Resistor |
| RT | Thermistor |
| S | Switch |
| T | Transformer |
| TP | Test Point |
| U | Component Network, Integrated Circuit, |
| V | Circuit Assembly |
| W | Photocell/Vacuum Tube |
| Y | Waveguide |

Table 1 (Continued)
Abbreviations


The above is only a sample. The actual format and style may vary slightly. A 'Find Number' column, when shown, references selected items on the BOM's accompanying Assembly Drawing. This information does not apply to every BOM. Therefore, a lack of information in this column, or a lack of this column, should not be interpreted as an omission.

Figure 6-1
Sample Parts List

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### 6.5 KI 525 FINAL ASSEMBLY

066-03029-0000 Rev. 12
066-03029-0001 Rev. 12

| SYMBOL | PART NUMBER | FIND N0 | DESCRIPTION | UM | 0000 | 0001 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 012-01005-0004 |  | TAPE MYLAR 2.250 W | IN | 7.20 | 7.20 |
|  | 016-01005-0000 |  | EPOXY KIT 3M 40CC | AR | . 00 | . 00 |
|  | 016-01008-0004 |  | GLYPTAL 7526 BL | AR | . 00 | 00 |
|  | 016-01095-0000 |  | ADHESIVE \#7085 | AR | . 00 | . 00 |
|  | 025-00018-0000 |  | WIRE 26 BLK | IN | 3.60 | 3.60 |
|  | 025-00018-0015 |  | WIRE 26 BN/GN | IN | 1.20 | 1.20 |
|  | 025-00018-0016 |  | WIRE 26 BN/BU | IN | 3.60 | 3.60 |
|  | 025-00018-0020 |  | WIRE 26 RD/BK | IN | 1.20 | 1.20 |
|  | 025-00018-0021 |  | WIRE 26 RD/BN | IN | 3.60 | 3.60 |
|  | 025-00018-0022 |  | WIRE 26 RED | IN | 3.60 | 3.60 |
|  | 025-00018-0036 |  | WIRE 26 OR/BU | IN | 3.60 | 3.60 |
|  | 025-00018-0079 |  | WIRE $26 \mathrm{VI} / \mathrm{WH}$ | IN | 4.80 | 4.80 |
|  | 025-00018-0080 |  | WIRE 26 GY/BK | IN | 4.80 | 4.80 |
|  | 025-00018-0081 |  | WIRE 26 GY/BN | IN | 4.80 | 4.80 |
|  | 025-00018-0082 |  | WIRE 26 GY/RD | IN | 3.60 | 3.60 |
|  | 025-00018-0098 |  | WIRE 26 WH/GY | IN | 3.60 | 3.60 |
|  | 029-00257-0000 |  | GEAR SPUR 72T/64DP | EA |  | 1.00 |
|  | 047-02795-0001 |  | ENCLOSURE W/F | EA | 1.00 | 1.00 |
|  | 047-02802-0002 |  | ARM, GLIde Slope | EA | 1.00 | 1.00 |
|  | 047-02893-0001 |  | GS POINTER W/FINIS | EA | 2.00 | 2.00 |
|  | 057-01483-0001 |  | SERIAL NUMBER TAG | EA | 1.00 | 1.00 |
|  | 073-00070-0007 |  | KNOB HDG | EA | 1.00 | 1.00 |
|  | 073-00070-0008 |  | KNOB CRS | EA | 1.00 | 1.00 |
|  | 073-00493-0001 |  | CLMP SYNC | EA |  | . 00 |
|  | 088-00355-0002 |  | HOUSING PHTODET | EA | 1.00 | 1.00 |
|  | 089-05899-0003 |  | SCR PHP 2-56×3/16 | EA | 4.00 | 4.00 |
|  | 089-05899-0005 |  | SCR PHP \#2-56X5/16 | EA | 1.00 | 1.00 |
|  | 089-05903-0005 |  | SCR PHP 4-40X5/16 | EA | 8.00 | 8.00 |
|  | 089-06022-0005 |  | SCR SHC 2-56X5/16 | EA |  | 2.00 |
|  | 089-06024-0004 |  | SCR SHC 4-40X1/4 | EA | 1.00 | 1.00 |
|  | 089-06081-0003 |  | SCR PHP 4-40×3/16 | EA | 3.00 | 3.00 |
|  | 089-06200-0006 |  | SCR SET 2-56×3/16 | EA | 2.00 | 4.00 |
|  | 089-06204-0004 |  | SCR SET 4-40X1/8 | EA | 4.00 | 4.00 |
|  | 090-00233-0000 |  | PAD CONN SHORTING | EA | 1.00 | 1.00 |
|  | 134-05006-0000 |  | RES LT SEN 7.5K | EA | 1.00 | 1.00 |
|  | 148-00029-0000 |  | SYNCHRO XMTR | EA |  | 1.00 |
|  | 150-00003-0010 |  | TUBING TFLN 24AWG | IN | 12.00 | 12.00 |
|  | 150-00018-0010 |  | TUBING SHRINK WHT | IN | 9.60 | 10.80 |
|  | 200-00629-0000 |  | PC BD ASSY | EA | 1.00 | 1.00 |
|  | 200-00631-0000 |  | REAR GEAR PLT ASSY | EA | 1.00 | 1.00 |
|  | 200-00632-0000 |  | FRONT DISPLAY ASSY | EA | 1.00 | 1.00 |
|  | 200-00633-0000 |  | BEZEL ASSEMBLY | EA | 1.00 | 1.00 |
|  | 200-00643-0000 |  | GS PLATE ASSY | EA | 1.00 | 1.00 |

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FIGURE 6-2 KI 525 FINAL ASSEMBLY (Dwg. 300-00831-0000/0001 R-12)


FIGURE 6-2A KI 525 FINAL ASSEMBLY (Dwg. 300-00831-0000/0001 Old Revision)

### 6.6 KI 525 BEZEL ASSEMBLY

200-00633-0000 Rev. 12

| SYMBOL | PART NUMBER | FIND NO | DESCRIPTION | UM |
| :--- | :--- | :--- | :--- | ---: |
| REF1 | $300-00830-0000$ | BEZEL ASSEMBLY | RF | .000 |
|  | $012-05028-0001$ | GLASS COVER | EA | 1.00 |
|  | $016-01008-0004$ | GLYPTAL 7526 BL | AR | .00 |
|  | $016-01082-0000$ | DC RTV 3145 | AR | .00 |
|  | $047-02638-0001$ | CLAMP HLD DN | EA | 2.00 |
|  | $073-00370-0003$ | BEZEL | EA | 1.00 |
|  | $088-00356-0001$ | LIGHT WEDGE W/ C | EA | 1.00 |
|  | $089-05899-0003$ | SCR PHP $2-56 \times 3 / 16$ | EA | 2.00 |
|  | $187-01095-0000$ | GASKET FRONT | EA | 2.00 |

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FIGURE 6-3 KI 525 BEZEL ASSEMBLY
(Dwg. 300-00830-0000 R-AB)


### 6.7 KI 525 FRONT DISPLAY ASSEMBLY

200-00632-0000 Rev. CA

| SYMBOL | PART NUMBER | FIND No | DESCRIPTION | UM | 0000 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| REF1 | 300-00829-0000 |  | FRONT DISPLAY ASSY | RF | . 00 |
|  | 016-01008-0004 |  | GLYPTAL 7526 BL | AR | . 00 |
|  | 016-01013-0000 |  | VAC GREASE DC 976 | AR | . 00 |
|  | 016-01016-0000 |  | MOLYKOTE G-N PASTE | AR | . 00 |
|  | 016-01039-0000 |  | BLK BRSHG LCQR | AR | . 00 |
|  | 016-01122-0000 |  | EPOXY DEVCON 14250 | AR | . 00 |
|  | 029-00261-0000 |  | GEAR SPUR 40T/64DP | EA | 1.00 |
|  | 029-00264-0001 |  | GEAR FACE 64P | EA | 1.00 |
|  | 029-00265-0000 |  | GEAR CRWN 64P | EA | 1.00 |
|  | 029-00291-0000 |  | GEAR 20T/64DP | EA | 1.00 |
|  | 029-00292-0000 |  | GEAR 18T/64DP | EA | 1.00 |
|  | 029-00435-0000 |  | GEAR 36T | EA | 1.00 |
|  | 029-00435-0001 |  | GEAR 36T | EA | 2.00 |
|  | 029-00444-0000 |  | GEAR 24T | EA | 1.00 |
|  | 047-02749-0003 |  | THRUST WSHR 1.685 | EA | 1.00 |
|  | 047-02851-0000 |  | SHIM WASHER . 500 | EA | 4.00 |
|  | 047-02851-0002 |  | SHIM WASHER . 450 | AR | . 00 |
|  | 047-04390-0000 |  | STOP YOKE | EA | 1.00 |
|  | 076-00681-0003 |  | COLLAR, \#4-40 W/FI | EA | 2.00 |
|  | 076-00684-0000 |  | SHAFT HDG SELECT | EA | 1.00 |
|  | 076-00685-0000 |  | SHAFT CRS SELECT | EA | 1.00 |
|  | 076-00686-0000 |  | SHAFT DRIVE | EA | 1.00 |
|  | 088-00348-0002 |  | MASK | EA | 1.00 |
|  | 088-00349-0001 |  | POINTER COURSE | EA | 1.00 |
|  | 088-00350-0001 |  | TAIL COURSE | EA | 1.00 |
|  | 088-00719-0000 |  | SHAFT BUSHING 525A | EA | 3.00 |
|  | 089-05623-0003 |  | SCR PHP 0-80×3/16 | EA | 4.00 |
|  | 089-05853-0006 |  | SCR SET 2-56×3/16 | EA | 2.00 |
|  | 089-05857-0006 |  | SCR SET 4-40×3/16 | EA | 4.00 |
|  | 089-05903-0004 |  | SCR PHP 4-40X1/4 | EA | 2.00 |
|  | 089-05903-0005 |  | SCR PHP 4-40×5/16 | EA | 4.00 |
|  | 089-06022-0005 |  | SCR SHC 2-56X5/16 | EA | 2.00 |
|  | 089-06200-0004 |  | SCR SET 2-56X1/8 | EA | 1.00 |
|  | 089-06204-0010 |  | SCR SET 6-32×5/16 | EA | 3.00 |
|  | 089-06414-0005 |  | SCR PHP 2-28X5/16 | EA | 4.00 |
|  | 089-08012-0037 |  | WSHR INTL LK \#2 | EA | 2.00 |
|  | 089-08054-0030 |  | WSHR FLT STD . 128 | EA | 10.00 |
|  | 089-08077-0030 |  | WASHER | AR | . 00 |
|  | 089-08162-0000 |  | WSHR FLT RVT . 068 | AR | . 00 |
|  | 089-08204-0001 |  | WSHR SPR . 390 | EA | 2.00 |
|  | 090-00019-0000 |  | RING RTNR . 125 | EA | 2.00 |
|  | 090-00036-0001 |  | RING RTNR . 094 | EA | 1.00 |
|  | 090-00188-0000 |  | GRIP RING | EA | 2.00 |
|  | 200-00622-0000 |  | FLAG MCHNSM ASSY | EA | 1.00 |
|  | 200-00622-0001 |  | FLAG MCHNSM ASSY | EA | 1.00 |
|  | 200-00624-0000 |  | DIFF CARRIER ASSY | EA | 1.00 |
|  | 200-00625-0000 |  | YOKE ASSY | EA | 1.00 |

```
SYMBOL PART NUMBER FIND NO DESCRIPTION UM 0000
    200-00626-0000 SYNC GEAR PLT ASSY EA 1.00
    200-00627-0000 FRONT FRAME ASSY EA 1.00
```



FIGURE 6-4 KI 525 FRONT DISPLAY ASSEMBLY (Dwg. 300-00829-0000 R-CB, Sheet 1 of 2)


FIGURE 6-4 KI 525 FRONT DISPLAY ASSEMBLY
(Dwg. 300-00829-0000 R-CB, Sheet 2 of 2)
notes:
2. FOR COMPLETE DESCRIPTION OF PARTS SEE B/M $200-0632$-O0,01,-02,-03,-O4




ASSEVERY
OF Topave.
3. DRive shaft fig. 3 ) wust be as






$A S$ REMPRD











4. Assembly to be marked prid ol-otiol-oxoo in approximate area shown


FIGURE 6-4A KI 525 FRONT DISPLAY ASSEMBLY (Dwg. 300-00829-0000 Old Revision, Sheet 1 of 2)


HEADING SELECT SHAFT ASSEMBLY
FIGURE I (SEE NOTE 2)


COURSE SELECT SHAFT ASSEMBLY
FIGURE 2 (SEE NOTE 3 )

vores
1- For complete nescription of parts see b/M 200-0632-00
2- reading select shaft (fig: 1) must be assembiled as followed
A - Slide gear ( $029-0259-00$ ) on to shaft (076-0684-00) and locate as PER DRAWING. APPLY AdHESIVE ( $016-1029-00$ ) to gear and Shaft as
B - after adhesine has cured insert shaft and gear into front frame assy (200-0627-00) with gean to rfar of init, attach petahimig RTVG (0090-0041-00) TO GROVVE IN SHAFT.

- course sflect shaft (fig. 2) must be assemblled as follows

A - SLIDE Gear ( $029-0261-00$ ) onto shaft ( $076-0685-00$ ) and locate as as per spec.
 Eront frame assembly (200-0627-00) far enoug to allow gear end of SHAFT TO be inserted into sychro plate,
against disp broperiy positioned slide wavy washer and collar snug


- drive suaft (fis in mist be assembled as follows.
 255 029-0291-00 AND (029-0292-00), (NOTE-GEAR MUST be oN Froit side of plate.
B - INSERT GEAR (029-(26nnoo \& 029-0255-00) AND WASHER (047-2851-01) INTO POCKET IN FRONT FRRME AND PRESS SHAFT (076-068 $6-00$ ) TH them as shown in fig. 3.

ov - No adhesive shat pexail onate as shown in fig. 3
6-apply glyptal (016-1008-04) to all screws.
- miring assembiy extreme care shall be taken to prevent scratching or marring finish on mask (088-0348-01) and azimuth dial on front frame assembly (200-0627-00).

8.     - COIRSE POINTER (088-0349-01) AND TALL (088-0350-01) ARE NOT ATTACHED UNTLI YOKE ASSEMBLY ( $200-0625-00$ ) AND FRONT FRAME ASSEMBLY (200-0627-00 are assembled. after assembly apply adequate amount of adhesive
$(016-1029-00)$ to rear of pointer and tail avd install on nav mask ( 088 - 0347 -01). AFTER ADHESIVE HAS CURED, TOUCH UP ALL AREAS WHERE THE ADHESIVE IS VISIBLE WITH BLACK BRUSHING LACQUER ( 016 -1039-00) COURSE PONTTER (O88-0349-01) AND TAIL ( 088 -0350-01) WILL BE SUPPLIED with ass'y 200-0625-00 but not installed until this level of ass'y,
. when securing gears to shafts, clean both surfaces with chlorathane before applying adeessive.

FIGURE 6-4A KI 525 FRONT DISPLAY ASSEMBLY
(Dwg. 300-00829-0000 Old Revision, Sheet 2 of 2)

### 6.8 KI 525 FRONT FRAME ASSEMBLY

200-00627-0000 Rev. AA

| SYMB0L | PART NUMBER | FIND NO | DESCRIPTION | UM | 0000 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| REF100 | 300-00824-0000 |  | ASSEMBLY, FRONT FR | RF | . 00 |
|  | 016-01103-0000 |  | MOLYKOTE 33 MED DC | AR | . 00 |
|  | 047-02749-0001 |  | THRUST WSHR 2.140 | EA | 2.00 |
|  | 047-02749-0002 |  | THRUST WSHR 1.970 | EA | 1.00 |
|  | 047-02749-0004 |  | THRUST WASHER 2.14 | EA | 1.00 |
|  | 047-02807-0001 |  | WAVY WASHER W/HT | EA | 1.00 |
|  | 073-00216-0003 |  | FRAME FRONT | EA | 1.00 |
|  | 088-01069-0002 |  | DIAL AZIMUTH W/SS | EA | 1.00 |
|  | 090-00210-0000 |  | RTNG RING (SPECIAL | EA | 1.00 |
|  | 090-00227-0000 |  | BALL STEEL | AR | . 00 |
|  | 090-00230-0000 |  | BALL STEEL | AR | . 00 |
|  | 090-00339-0000 |  | STEEL BALL | AR | . 00 |
|  | 091-00203-0002 |  | SCR FHS 0-80X. 125 | EA | 3.00 |
|  | 200-00536-0000 |  | HDG SELECT ASSY | EA | 1.00 |

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FIGURE 6-5 KI 525 FRONT FRAME ASSEMBLY (Dwg. 300-00824-0000 R-AB)

NOTY:
1-SEE B/M 200-0627-00 FOR COMPlete DESCRIPTION of parts.
2 - Apply glyptal (016-1008-04) to all SCREWs.
3 - AFTER ASSEMBLY, THE (029-0268-01) GEAR SHOULD ROTATE WITH AN APPLIED TORQUE OF 1.3 OZ - INCHE
MAXIMUM. THERE SHALL BE NO POSITION FROM WHICH THE GEAR WILL NOT BEGIN TO ROTATE WITH THIS APPLLED TORQUES?

4 - EXERCISE CAUTION WHEN HANDLING THE HEADING SELECT GEAR ASSEMBLY (200-0536-00) AND TH
AZIMUTH DIAL ( $076-0688-01$ ) TO INSURE THAT AZIMUTH DIAL (076-0688-01) TO 1 NSURL THAT
THEIR PAINTED SURFACES REMAIN CLEAN AND THEIR PAINTED.
UNBLEMISHED.

- WITH THE 029-0258-01 GEAR HELD STATIONARY THE



## FIGURE 6-5A KI 525 FRONT FRAME ASSEMBLY

Dwg. 300-00824-0000 Old Revision)

### 6.9 KI 525 HEADING SELECT GEAR ASSEMBLY

200-00536-0000 Rev. AA

| SYMBOL | PART NUMBER | FIND N0 | description | UM | 0000 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| REF100 | 300-00738-0000 |  | ASSY, HEADING SELE | RF | . 00 |
|  | 047-02743-0001 |  | HDG SLCT MRKR W/F | EA | 1.00 |
|  | 092-00034-0002 |  | RVT OH 1/32X.062 | EA | 2.00 |
|  | 200-09731-0000 |  | KI 525A GEAR SET, | EA | 1.00 |

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## NOTES:

I-FOR COMPLETE DESCRIPTION OF ITEMS SEE B/M 200-0536-00


FIGURE 6-6 KI 525 HEADING SELECT GEAR ASSEMBLY (Dwg. 300-00738-0000 R-AA)

IFOR COMPLETE DESCRIPTION OF ITEMS
SEE B/M $200-0536-00$
2-DURING AND AFTER ASSEMBLY CARE SHALL
BE USED TO PREVENT SCRATCING OR marring finish of pointer.

MOTE-MANUFACTUREO HEAD

## SECTIONAL VIEW <br> AFTER POLNTER HAS BEEN ATTACHED

## FIGURE 6-6A KI 525 HEADING SELECT GEAR ASSEMBLY

## (Dwg. 300-00738-0000 Old Revision)

6.10 KI 525 HEADING GEAR SET ASSEMBLY

200-09731-0000 Rev. -

| SYMB0L | PART NUMBER | FIND NO | DESCRIPTION | UM | 0000 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| REF1 | 300-09731-0000 |  | KI 525A GEAR SET, | RF | . 00 |
|  | 029-00267-0001 |  | GEAR HDG SLCT 64P | EA | 1.00 |
|  | 029-00268-0001 |  | GEAR HDG 64P | EA | 1.00 |

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NOTES

1. this drawing defines a matched set of gears with a radial clearance as shown in addition to the radial clearance, the gears must turn freely WHEN MATED AS SHOWN WITH NO TENDENCY TO BIND.
this drawing is not complete without part list 200-09731-0000
2. protective packaging: individually package assemblies in plastic bags

### 6.11 KI 525 SYNCHRO PLATE ASSEMBLY

200-00626-0000 Rev. 5

| SYMB0L | PART NUMBER | FIND NO | DESCRIPTION | UM | 0000 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| B102 | 148-00028-0000 |  | SYNCHRO VCTR RSLVR | EA | 1.00 |
| B104 | 148-00013-0000 |  | SYNCHRO CONT XFMR | EA | 1.00 |
| REF100 | 300-00823-0000 |  | SYNCHRO GEAR ASSY | RF | . 00 |
|  | 029-00257-0000 |  | GEAR SPUR 72T/64DP | EA | 1.00 |
|  | 073-00213-0001 |  | CLAMP SYNCHRO | EA | 2.00 |
|  | 073-00221-0003 |  | GEAR PLATE SYNC | EA | 1.00 |
|  | 073-00493-0001 |  | CLMP SYNC | EA | 2.00 |
|  | 089-06022-0005 |  | SCR SHC 2-56X5/16 | EA | 4.00 |
|  | 089-06200-0008 |  | SCR SET 2-56X1/4 | EA | 2.00 |

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FIGURE 6-8 KI 525 SYNCHRO PLATE ASSEMBLY (Dwg. 300-00823-0000 R-AA)


### 6.12 KI 525 YOKE ASSEMBLY

200-00625-0000 Rev. AA

| SYMB0L | PART NUMBER | FIND NO | DESCRIPTION | UM | 0000 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| REF100 | 300-00822-0000 |  | YOKE ASSEMBLY KI52 | RF | . 00 |
|  | 023-00083-0000 |  | MTR TO/FR FLAG | EA | 1.00 |
|  | 023-00084-0000 |  | IND DEVIATION | EA | 1.00 |
|  | 047-02849-0001 |  | CONTACT RING W/FIN | EA | 4.00 |
|  | 088-00346-0000 |  | YOKE | EA | 1.00 |
|  | 088-00347-0002 |  | MASK | EA | 1.00 |
|  | 088-00387-0000 |  | GUARD | EA | 2.00 |
|  | 089-05899-0003 |  | SCR PHP 2-56X3/16 | EA | 4.00 |
|  | 089-07046-0004 |  | SCR PHS 2-56X1/4 | EA | 4.00 |

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FIGURE 6-9A KI 525 YOKE ASSEMBLY
(Dwg. 300-00822-0000 Old Revision)

### 6.13 KI 525 DIFFERENTIAL CARRIER ASSEMBLY <br> 200-00624-0000 Rev. 1

| SYMBOL | PART NUMBER | FIND NO | DESCRIPTION | UM | 0000 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| REF100 | 300-00821-0000 |  | DIFF CARRIER ASSY | RF | . 00 |
|  | 029-00256-0000 |  | GEAR SPUR 16T/64DP | EA | 2.00 |
|  | 029-00262-0001 |  | GEAR SPUR 160T/64P | EA | 1.00 |
|  | 047-02850-0000 |  | SHIM WASHER | EA | 4.00 |
|  | 076-00693-0000 |  | PIN SPIDER GEAR | EA | 2.00 |

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FIGURE 6-10A KI 525 DIFFERENTIAL CARRIER ASSEMBLY (Dwg. 300-00821-0000 Old Revision)

### 6.14 KI 525 FLAG MECHANISM ASSEMBLY <br> 200-00622-0000 Rev. AA <br> 200-00622-0001 Rev. AA

| SYMB0L | PART NUMBER | FIND NO | DESCRIPTION | UM | 0000 | 0001 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| REF100 | 300-00819-0000 |  | FLAG MECHANISM AS | RF | . 00 |  |
|  | 016-01082-0000 |  | DC RTV 3145 | AR | 1.00 | 1.00 |
|  | 016-01114-0000 |  | EPXY TRA-CAST 3103 | AR | . 00 | . 00 |
|  | 019-02185-0001 |  | COIL FLG MCH 1430T | EA | 1.00 | 1.00 |
|  | 047-02847-0006 |  | POLE . $430 \mathrm{~W} / \mathrm{F}$ | EA | 1.00 | 1.00 |
|  | 047-02847-0007 |  | POLE . $523 \mathrm{~W} / \mathrm{F}$ | EA | 1.00 | 1.00 |
|  | 047-02848-0001 |  | SPACER POLE W/F | EA | 2.00 | 2.00 |
|  | 088-00344-0000 |  | HSG FLAG | EA | 1.00 | 1.00 |
|  | 088-00345-0001 |  | COVER FLAG | EA | 1.00 | 1.00 |
|  | 090-00186-0000 |  | RETAINER RING | EA | 1.00 | 1.00 |
|  | 200-00642-0001 |  | FLAG ASSY | EA | . | 1.00 |
|  | 200-00642-0003 |  | FLAG ASSY | EA | 1.00 | . |
|  | 300-00819-0001 |  | FLAG MECHANISM ASS | RF | . | . 00 |

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notes:
I FOR COMPLETE ITEM DESCRIPTION SEE B/M 200-0622-00
2 APPLY ADHESIVE (016-1114-00) INSIDE
H
ALL PARTS \& COVER (088-0345-01)
3 AFTER GRIP RING (090-0186-00) ISINSTAL
AFTER GRIP RING (O9O-OIB6-OO) ISINSTALLED
THE FLAG ASSEMBLY SHOULD HVE.OLO THE FLAG ASSEMBLY SHOUL HAEE.OLO
INCHES AXIALCLEARANCE BETWEEN TH
COVER COVER (O88-0345-OI) AND GRIP RING, 4 AFTER ASSEMBLY THE D.C.RESISTANCE BETWEEN 5. ADD A 3/8 INCH DIAMETER SERVICE LOOP TO THE LEADS COMING FROM THE COIL
6. NOTE DELETED

[^0] fLow down shaft.

FIGURE 6-11 KI 525 FLAG MECHANISM ASSEMBLY (Dwg. 300-00819-0000 R-AB)


FIGURE 6-11A KI 525 FLAG MECHANISM ASSEMBLY
(Dwg. 300-00819-0000 Old Revision)


FIGURE 6-12 KI 525 FLAG MECHANISM ASSEMBLY (Dwg. 300-00819-0001 R-AB)


FIGURE 6-12A KI 525 FLAG MECHANISM ASSEMBLY (Dwg. 300-00819-0001 Old Revision)

### 6.15 KI 525 FLAG ASSEMBLY

$$
\begin{array}{ll}
200-00642-0001 & \text { Rev. AB } \\
200-00642-0003 & R e v . ~ A A
\end{array}
$$

| SYMBOL | PART NUMBER | Find No | DESCRIPTION | UM | 0001 | 0003 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| REF100 | 300-05545-0000 |  | NAV FLAG ASSY | RF |  | . 00 |
|  | 013-00017-0000 |  | MAGNET | EA | 1.00 | 1.00 |
|  | 016-01122-0000 |  | EPOXY DEVCON 14250 | AR | 1.00 | 1.00 |
|  | 047-02841-0002 |  | FLAG PWR | EA | 1.00 |  |
|  | 047-10437-0003 |  | FLAG | EA |  | 1.00 |
|  | 300-00838-0001 |  | FLAG ASSY | RF | . 00 |  |

$$
\begin{array}{ll}
200-00642-0000 & \text { Rev. AA } \\
200-00642-0002 & \text { Rev. AA }
\end{array}
$$

SYMBOL PART NUMBER FIND NO DESCRIPTION UM 00000002
013-00017-0000 MAGNET EA 1.00 1.00
016-01122-0000 EPOXY DEVCON 14250 AR 1.001 .00
$\begin{array}{lll}047-02841-0001 & \text { FLAG } & \text { EA } 1.00 \\ 047-02841-0003 & \text { FLAG } & \text { EA }\end{array}$

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NOTES:

1. HOLES MUST BE CONCENTRIC.
2. NO ADHESIVE SHALL REMAIN IN BORE AFTER ASSEMBLY.

THIS DRAWING NOT COMPLETE WITHOUT PARTS LIST 200-00642-0003.

FIGURE 6-13 FLAG ASSEMBLY
(Dwg. 300-05545-0000 Rev. AA)

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## NOTES:

1-HOLES MUST BE CONCENTRIC
2-NO ADHESIVE SHALL REMAIN IN BORE AFTER ASSEMBLY
3-SEE B/M 200-0642-00 FOR COMPLETE PART DESCRIFTION.

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NOTES:
I-HOLES MUST BE CONCENTRIC
2-NO ADHESIVE SHALL REMAIN IN BORE AFTER ASSEMBLY
3-AFTER MAGNET AND FLAG ARE ASSEMBLED APPLY OI6-1029-00 (EPOXY POTTING KIT OOI BA) TO REAR OF ASSEMBLY AS INDICATED ON DRAWING. CAUTION - NO EPOXY SHALL APPEAR ON FRONT OF ASSEMBLY.

FIGURE 6-14A FLAG ASSEMBLY
(Dwg. 300-00838-0000 Old Revision)

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NOTES:
1-HOLES MUST BE CONCENTRIC
2-NO ADHESIVE SHALL REMAIN IN BORE AFTER ASSEMBLY.
3-SEE B/M 200-0642-OI FOR COMPLETE PART DESCRIPTION.

FIGURE 6-15 FLAG ASSEMBLY
(Dwg. 300-00838-0001 Rev. AA)

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## 016-1029-00

ADHESIVE SEE NOTE 3


NOTES:
1-HOLES MUST BE CONCENTRIC
2-NO ADHESIVE SHALL REMAIN IN BORE
AFTER ASSEMBLY.
3-AFTER MAGNET AND FLAG ARE ASSEMBLED APPLY OI6-1029-OO (EPOXY POTTING KIT 001 BA) TO REAR OF ASSEMBLY AS INDICATED ON DRWG, CAUTION-NOEPOXY SHALL APPEAR ON FRONT OFASSEMBLY.

FIGURE 6-15A FLAG ASSEMBLY
(Dwg. 300-00838-0001 Old Revision)

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### 6.16 KI 525 REAR PLATE ASSEMBLY

200-00631-0000 Rev. AB

| SYMB0L | PART NUMBER | FIND NO | DESCRIPTION | UM | 0000 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| B103 | 148-05035-0000 |  | MOTOR STEPPER | EA | 1.00 |
| J102 | 030-02179-0000 |  | CONN 41 PIN FEM | EA | 1.00 |
| REF100 | 300-00828-0000 |  | ASSEMBLY, REAR GEA | RF | . 00 |
|  | 016-01007-0005 |  | LOCTITE 222 | AR | 1.00 |
|  | 016-01268-0000 |  | LOCTITE 271 | AR | 1.00 |
|  | 029-00352-0000 |  | GEAR 12/35T | EA | 2.00 |
|  | 029-00404-0000 |  | GEAR 14T | EA | 1.00 |
|  | 030-01007-0000 |  | TAB LOCKING | EA | 2.00 |
|  | 047-04782-0002 |  | PLATE W/F \& PVT | EA | 1.00 |
|  | 073-00222-0003 |  | GEAR PLATE REAR | EA | 1.00 |
|  | 076-00820-0001 |  | SPACER - COVER | EA | 1.00 |
|  | 089-05903-0003 |  | SCR PHP 4-40×3/16 | EA | 2.00 |
|  | 089-06022-0004 |  | SCR SHC 2-56X1/4 | EA | 2.00 |
|  | 090-00186-0000 |  | RETAINER RING | EA | 2.00 |
|  | 150-00018-0010 |  | TUBING SHRINK WHT | IN | 1.20 |

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FIGURE 6-16 KI 525 REAR PLATE ASSEMBLY

note






## FIGURE 6-16A KI 525 REAR PLATE ASSEMBLY

(Dwg. 300-00828-0000 Old Revision)

### 6.17 KI 525 P.C. BOARD ASSEMBLY

200-00629-0000 Rev. 18

| SYMBOL | PART NUMBER | FIND NO | DESCRIPTION | UM | 0000 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| C101 | 111-00001-0026 |  | CAP CR .33UF 50V | EA | 1.00 |
| C104 | 111-00001-0030 |  | CAP CR .68UF 50V | EA | 1.00 |
| C105 | 111-00001-0028 |  | CAP CR .47UF 50V | EA | 1.00 |
| C108 | 096-01030-0005 |  | CAP TN 10UF 10\%20V | EA | 1.00 |
| C109 | 096-01030-0005 |  | CAP TN 10UF 10\%20V | EA | 1.00 |
| C110 | 096-01074-0002 |  | CAPACITOR | EA | 1.00 |
| C115 | 111-00001-0000 |  | CAP CR . O1UF 50V | EA | 1.00 |
| C116 | 111-00001-0030 |  | CAP CR .68UF 50V | EA | 1.00 |
| C117 | 111-00001-0030 |  | CAP CR . 68UF 50V | EA | 1.00 |
| C119 | 111-00001-0006 |  | CAP CR . 47 UF 50 V | EA | 1.00 |
| C120 | 111-02821-0051 |  | CAP MC 820PF100V10 | EA | 1.00 |
| C121 | 113-03121-0000 |  | CAP DC 120PF 500V | EA | 1.00 |
| C122 | 113-03121-0000 |  | CAP DC 120PF 500V | EA | 1.00 |
| C123 | 113-03121-0000 |  | CAP DC 120PF 500V | EA | 1.00 |
| C124 | 111-00001-0012 |  | CAP CR . 047UF 50V | EA | 1.00 |
| C125 | 111-00001-0012 |  | CAP CR .047UF 50V | EA | 1.00 |
| CJ101 | 026-00018-0001 |  | WIRE CKTJMPR 24AWG | EA | 1.00 |
| CJ102 | 026-00018-0001 |  | WIRE CKTJMPR 24AWG | EA | 1.00 |
| CJ105 | 026-00018-0001 |  | WIRE CKTJMPR 24AWG | EA | 1.00 |
| CJ106 | 026-00018-0001 |  | WIRE CKTJMPR 24AWG | EA | 1.00 |
| CR101 | 007-06023-0000 |  | DIO G 1N277 | EA | 1.00 |
| CR102 | 007-06023-0000 |  | DIO G 1N277 | EA | 1.00 |
| CR103 | 007-06029-0000 |  | DIO S 1N457A | EA | 1.00 |
| CR104 | 007-05045-0009 |  | DIO Z 1/4M5.1AZ5 | EA | 1.00 |
| CR105 | 007-05044-0012 |  | DIO Z 1N5530B 10V | EA | 1.00 |
| CR106 | 007-06029-0000 |  | DIO S 1N457A | EA | 1.00 |
| CR107 | 007-06085-0000 |  | DIO HC 1N5711 | EA | 1.00 |
| CR108 | 007-05045-0009 |  | DIO Z 1/4M5.1AZ5 | EA | 1.00 |
| CR109 | 007-06029-0000 |  | DIO S 1N457A | EA | 1.00 |
| CR110 | 007-05044-0012 |  | DIO Z 1N5530B 10V | EA | 1.00 |
| CR111 | 007-07004-0001 |  | SOLID STATE LAMP | EA | 1.00 |
| CR114 | 007-05051-0007 |  | DIO Z 1N825A | EA | 1.00 |
| CR115 | 007-07004-0000 |  | DIO L 5082-4480 | EA | 1.00 |
| CR116 | 007-06029-0000 |  | DIO S 1N457A | EA | 1.00 |
| CR119 | 007-05011-0017 |  | DIO Z 11V 1W 5\% | EA | 1.00 |
| CR120 | 007-06029-0000 |  | DIO S 1N457A | EA | 1.00 |
| CR121 | 007-06029-0000 |  | DIO S 1N457A | EA | 1.00 |
| CR122 | 007-06029-0000 |  | DIO S 1N457A | EA | 1.00 |
| CR123 | 007-06029-0000 |  | DIO S 1N457A | EA | 1.00 |
| CR124 | 007-06029-0000 |  | DIO S 1N457A | EA | 1.00 |
| CR125 | 007-06029-0000 |  | DIO S 1N457A | EA | 1.00 |
| CR126 | 007-06029-0000 |  | DIO S 1N457A | EA | 1.00 |
| CR127 | 007-05044-0009 |  | DIO Z 1N5527B | EA | 1.00 |
| CR128 | 007-05044-0009 |  | DIO Z 1N5527B | EA | 1.00 |
| CR129 | 007-06029-0000 |  | DIO S 1N457A | EA | 1.00 |
| CR130 | 007-06029-0000 |  | DIO S 1N457A | EA | 1.00 |
| DS101 | 037-00028-0006 |  | LMP 5640 T1-1/4 14 | EA | 1.00 |
| DS102 | 037-00028-0006 |  | LMP 5640 T1-1/4 14 | EA | 1.00 |
| Rev 7, July/2001 |  |  | 15620M07.JA |  |  |


| SYMBOL | PART NUMBER | FIND N0 | DESCRIPTION | UM | 0000 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| I101 | 120-03053-0010 |  | IC LM2904 S0 PKG | EA | 1.00 |
| I102 | 120-03053-0010 |  | IC LM2904 SO PKG | EA | 1.00 |
| I103 | 120-03052-0007 |  | IC LM224D | EA | 1.00 |
| I105 | 120-03052-0007 |  | IC LM224D | EA | 1.00 |
| J101 | 030-02152-0000 |  | CONN 24P MALE | EA | 1.00 |
| Q104 | 007-00026-0003 |  | XSTR S NPN 2 N3416 | EA | 1.00 |
| Q109 | 007-00038-0000 |  | XSTR S NPN 2N3053 | EA | 1.00 |
| R104 | 131-00391-0023 |  | RES CF 390 QW 5\% | EA | 1.00 |
| R105 | 131-00391-0023 |  | RES CF 390 QW 5\% | EA | 1.00 |
| R106 | 131-00273-0013 |  | RES CF 27K EW 5\% | EA | 1.00 |
| R107 | 131-00393-0013 |  | RES CF 39K EW 5\% | EA | 1.00 |
| R108 | 131-00222-0013 |  | RES CF 2.2K EW 5\% | EA | 1.00 |
| R109 | 132-00107-0059 |  | RES WW 130 3.25W5\% | EA | 1.00 |
| R110 | 131-00102-0033 |  | RES CF 1K HW 5\% | EA | 1.00 |
| R111 | 136-01003-0062 |  | RES PF 100K EW 1\% | EA | 1.00 |
| R112 | 136-01052-0062 |  | RES PF 10.5K EW 1\% | EA | . 10 |
| R112 | 136-01072-0062 |  | RES PF 10.7K EW 1\% | EA | . 10 |
| R112 | 136-01102-0062 |  | RES PF 11K EW 1\% | EA | . 10 |
| R112 | 136-01132-0062 |  | RES PF 11.3K EW 1\% | EA | 10 |
| R112 | 136-01152-0062 |  | RES PF 11.5K EW 1\% | EA | . 10 |
| R112 | 136-01182-0062 |  | RES PF 11.8K EW 1\% | EA | . 10 |
| R112 | 136-01212-0062 |  | RES PF 12.1K EW 1\% | EA | . 10 |
| R113 | 136-02211-0062 |  | RES PF 2.21K EW 1\% | EA | 1.00 |
| R114 | 131-00242-0033 |  | RES CF 2.4K HW 5\% | EA | 1.00 |
| R115 | 131-00102-0013 |  | RES CF 1K EW 5\% | EA | 1.00 |
| R116 | 131-00364-0013 |  | RES CF 360K EW 5\% | EA | 1.00 |
| R117 | 136-01003-0062 |  | RES PF 100K EW 1\% | EA | 1.00 |
| R118 | 136-01003-0062 |  | RES PF 100K EW 1\% | EA | 1.00 |
| R119 | 131-00181-0023 |  | RES CF 180 QW 5\% | EA | 1.00 |
| R120 | 131-00181-0023 |  | RES CF 180 QW 5\% | EA | 1.00 |
| R121 | 136-02492-0062 |  | RES PF 24.9K EW 1\% | EA | 1.00 |
| R122 | 136-02492-0062 |  | RES PF 24.9K EW 1\% | EA | 1.00 |
| R123 | 136-01001-0062 |  | RES PF 1K EW 1\% | EA | 1.00 |
| R124 | 136-02003-0062 |  | RES PF 200K EW 1\% | EA | 1.00 |
| R125 | 136-05111-0062 |  | RES PF 5.11K EW 1\% | EA | 1.00 |
| R126 | 136-01101-0062 |  | RES PF 1.10K EW 1\% | EA | 1.00 |
| R127 | 136-05111-0062 |  | RES PF 5.11K EW 1\% | EA | 1.00 |
| R128 | 136-02003-0062 |  | RES PF 200K EW 1\% | EA | 1.00 |
| R129 | 136-05112-0062 |  | RES PF 51.1K EW 1\% | EA | 1.00 |
| R130 | 136-04752-0062 |  | RES PF 47.5K EW 1\% | EA | 1.00 |
| R131 | 131-00204-0013 |  | RES CF 200K EW 5\% | EA | 1.00 |
| R133 | 131-00181-0023 |  | RES CF 180 QW 5\% | EA | 1.00 |
| R134 | 131-00333-0013 |  | RES CF 33K EW 5\% | EA | 1.00 |
| R135 | 136-02001-0062 |  | RES PF 2K EW 1\% | EA | 1.00 |
| R136 | 136-02001-0062 |  | RES PF 2K EW 1\% | EA | 1.00 |
| R137 | 136-03013-0062 |  | RES PF 301K EW 1\% | EA | 1.00 |
| R138 | 136-05111-0062 |  | RES PF 5.11K EW 1\% | EA | 1.00 |
| R139 | 136-01101-0062 |  | RES PF 1.10K EW 1\% | EA | 1.00 |
| R140 | 136-05111-0062 |  | RES PF 5.11K EW 1\% | EA | 1.00 |
| R141 | 136-03013-0062 |  | RES PF 301K EW 1\% | EA | 1.00 |
| R142 | 131-00623-0013 |  | RES CF 62K EW 5\% | EA | 1.00 |
| R143 | 131-00113-0013 |  | RES CF 11K EW 5\% | EA | 1.00 |


| SYMBOL | PART NUMBER | FIND NO | DESCRIP | PTION | UM | 0000 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| R144 | 131-00153-0013 |  | RES CF | 15K EW 5\% | EA | 1.00 |
| R145 | 136-02553-0062 |  | RES PF | 255K EW 1\% | EA | 1.00 |
| R146 | 136-01333-0062 |  | RES PF | 133K EW 1\% | EA | 1.00 |
| R146 | 136-01373-0072 |  | RES PF | 137K QW 1\% | EA | 1.00 |
| R147 | 133-00100-0074 |  | RES VA | 200K QW 10\% | EA | 1.00 |
| R148 | 136-02553-0062 |  | RES PF | 255K EW 1\% | EA | 1.00 |
| R149 | 131-00911-0013 |  | RES CF | 910 EW 5\% | EA | 1.00 |
| R150 | 131-00114-0013 |  | RES CF | 110K EW 5\% | EA | 1.00 |
| R151 | 131-00513-0013 |  | RES CF | 51K EW 5\% | EA | 1.00 |
| R153 | 131-00222-0023 |  | RES CF | 2.2K QW 5\% | EA | 1.00 |
| R154 | 132-00105-0053 |  | RES WW | 91 1.5W 5\% | EA | 1.00 |
| R160 | 131-00364-0013 |  | RES CF | 360K EW 5\% | EA | 1.00 |
| R161 | 131-00132-0013 |  | RES CF | 1.3K EW 5\% | EA | 1.00 |
| R162 | 131-00753-0013 |  | RES CF | 75K EW 5\% | EA | 1.00 |
| R164 | 131-00513-0013 |  | RES CF | 51K EW 5\% | EA | 1.00 |
| R165 | 131-00104-0013 |  | RES CF | 100K EW 5\% | EA | 1.00 |
| R166 | 131-00683-0013 |  | RES CF | 68K EW 5\% | EA | 1.00 |
| R167 | 136-07502-0062 |  | RES PF | 75.0K EW 1\% | EA | 1.00 |
| R168 | 131-00513-0013 |  | RES CF | 51K EW 5\% | EA | 1.00 |
| R169 | 133-00100-0075 |  | RES VA | 250K QW 10\% | EA | 1.00 |
| R170 | 133-00100-0076 |  | RES VA | 500K QW 10\% | EA | 1.00 |
| R171 | 132-00105-0053 |  | RES WW | 91 1.5W 5\% | EA | 1.00 |
| R172 | 132-00106-0076 |  | RES WW | 500 2.25W5\% | EA | 1.00 |
| R173 | 133-00100-0072 |  | RES VA | 50K QW 10\% | EA | 1.00 |
| R174 | 131-00184-0013 |  | RES CF | 180K EW 5\% | EA | 1.00 |
| R175 | 136-06042-0062 |  | RES PF | 60.4K EW 1\% | EA | 1.00 |
| R176 | 136-02743-0062 |  | RES PF | 274K EW 1\% | EA | 1.00 |
| R177 | 136-01003-0062 |  | RES PF | 100K EW 1\% | EA | . 01 |
| R177 | 136-01023-0062 |  | RES PF | 102K EW 1\% | EA | . 01 |
| R177 | 136-01053-0062 |  | RES PF | 105K EW 1\% | EA | . 01 |
| R177 | 136-01073-0062 |  | RES PF | 107K EW 1\% | EA | . 01 |
| R177 | 136-01103-0062 |  | RES PF | 110K EW 1\% | EA | . 01 |
| R177 | 136-01133-0062 |  | RES PF | 113K EW 1\% | EA | . 01 |
| R177 | 136-01153-0062 |  | RES PF | 115K EW 1\% | EA | . 01 |
| R177 | 136-01183-0062 |  | RES PF | 118K EW 1\% | EA | . 01 |
| R177 | 136-01213-0062 |  | RES PF | 121K EW 1\% | EA | 01 |
| R177 | 136-01243-0062 |  | RES PF | 124K EW 1\% | EA | . 01 |
| R177 | 136-01273-0062 |  | RES PF | 127K EW 1\% | EA | . 01 |
| R177 | 136-01303-0062 |  | RES PF | 130K EW 1\% | EA | . 01 |
| R177 | 136-01333-0062 |  | RES PF | 133K EW 1\% | EA | . 01 |
| R177 | 136-01373-0062 |  | RES PF | 137K EW 1\% | EA | . 01 |
| R177 | 136-01403-0062 |  | RES PF | 140K EW 1\% | EA | . 90 |
| R177 | 136-01433-0062 |  | RES PF | 143K EW 1\% | EA | . 01 |
| R177 | 136-01473-0062 |  | RES PF | 147K EW 1\% | EA | . 01 |
| R177 | 136-01503-0062 |  | RES PF | 150K EW 1\% | EA | . 01 |
| R177 | 136-01583-0062 |  | RES PF | 158K1/8W1\% | EA | . 01 |
| R177 | 136-01623-0062 |  | RES PF | 162K EW 1\% | EA | 01 |
| R177 | 136-01653-0062 |  | RES PF | 165K EW 1\% | EA | . 01 |
| R177 | 136-01693-0062 |  | RES PF | 169K EW 1\% | EA | . 01 |
| R177 | 136-01743-0062 |  | RES PF | 174K EW 1\% | EA | . 01 |
| R177 | 136-01783-0062 |  | RES PF | 178K EW 1\% | EA | . 01 |
| R177 | 136-01823-0062 |  | RES PF | 182K EW 1\% | EA | 01 |


| SYMB0L | PART NUMBER | FIND N0 | DESC | CRIPTION | UM | 0000 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| R177 | 136-01873-0062 |  | RES | PF 187K EW 1\% | EA | . 01 |
| R177 | 136-01913-0062 |  | RES | PF 191K EW 1\% | EA | . 01 |
| R177 | 136-01963-0062 |  | RES | PF 196K EW 1\% | EA | 01 |
| R177 | 136-02003-0062 |  | RES | PF 200K EW 1\% | EA | . 01 |
| R177 | 136-02053-0062 |  | RES | PF 205K EW 1\% | EA | . 01 |
| R177 | 136-02103-0062 |  | RES | PF 210K EW 1\% | EA | . 01 |
| R178 | 136-04873-0062 |  | RES | PF 487K EW 1\% | EA | 1.00 |
| R179 | 136-07502-0062 |  | RES | PF 75.0K EW 1\% | EA | 1.00 |
| R180 | 136-01433-0062 |  | RES | PF 143K EW 1\% | EA | 1.00 |
| R181 | 136-04873-0062 |  | RES | PF 487K EW 1\% | EA | 1.00 |
| R182 | 136-01003-0062 |  | RES | PF 100K EW 1\% | EA | . 01 |
| R182 | 136-01023-0062 |  | RES | PF 102K EW 1\% | EA | . 01 |
| R182 | 136-01053-0062 |  | RES | PF 105K EW 1\% | EA | 01 |
| R182 | 136-01073-0062 |  | RES | PF 107K EW 1\% | EA | . 01 |
| R182 | 136-01103-0062 |  | RES | PF 110K EW 1\% | EA | . 01 |
| R182 | 136-01133-0062 |  | RES | PF 113K EW 1\% | EA | . 01 |
| R182 | 136-01153-0062 |  | RES | PF 115K EW 1\% | EA | . 01 |
| R182 | 136-01183-0062 |  | RES | PF 118K EW 1\% | EA | . 01 |
| R182 | 136-01213-0062 |  | RES | PF 121K EW 1\% | EA | . 01 |
| R182 | 136-01243-0062 |  | RES | PF 124K EW 1\% | EA | . 01 |
| R182 | 136-01273-0062 |  | RES | PF 127K EW 1\% | EA | . 01 |
| R182 | 136-01303-0062 |  | RES | PF 130K EW 1\% | EA | . 01 |
| R182 | 136-01333-0062 |  | RES | PF 133K EW 1\% | EA | . 01 |
| R182 | 136-01373-0062 |  | RES | PF 137K EW 1\% | EA | . 01 |
| R182 | 136-01403-0062 |  | RES | PF 140K EW 1\% | EA | . 90 |
| R182 | 136-01433-0062 |  | RES | PF 143K EW 1\% | EA | . 01 |
| R182 | 136-01473-0062 |  | RES | PF 147K EW 1\% | EA | . 01 |
| R182 | 136-01503-0062 |  | RES | PF 150K EW 1\% | EA | . 01 |
| R182 | 136-01583-0062 |  | RES | PF 158K1/8W1\% | EA | . 01 |
| R182 | 136-01623-0062 |  | RES | PF 162K EW 1\% | EA | . 01 |
| R182 | 136-01653-0062 |  | RES | PF 165K EW 1\% | EA | . 01 |
| R182 | 136-01693-0062 |  | RES | PF 169K EW 1\% | EA | . 01 |
| R182 | 136-01743-0062 |  | RES | PF 174K EW 1\% | EA | . 01 |
| R182 | 136-01783-0062 |  | RES | PF 178K EW 1\% | EA | . 01 |
| R182 | 136-01823-0062 |  | RES | PF 182K EW 1\% | EA | . 01 |
| R182 | 136-01873-0062 |  | RES | PF 187K EW 1\% | EA | . 01 |
| R182 | 136-01913-0062 |  | RES | PF 191K EW 1\% | EA | . 01 |
| R182 | 136-01963-0062 |  | RES | PF 196K EW 1\% | EA | . 01 |
| R182 | 136-02003-0062 |  | RES | PF 200K EW 1\% | EA | . 01 |
| R182 | 136-02053-0062 |  | RES | PF 205K EW 1\% | EA | . 01 |
| R182 | 136-02103-0062 |  | RES | PF 210K EW 1\% | EA | . 01 |
| R183 | 136-02743-0062 |  | RES | PF 274K EW 1\% | EA | 1.00 |
| R184 | 131-00513-0013 |  | RES | CF 51K EW 5\% | EA | 1.00 |
| R185 | 134-01055-0000 |  | PTC | THERMISTOR | EA | 1.00 |
| R186 | 134-01055-0000 |  | PTC | THERMISTOR | EA | 1.00 |
| R187 | 131-00153-0013 |  | RES | CF 15K EW 5\% | EA | 1.00 |
| R188 | 131-00394-0013 |  | RES | CF 390K EW 5\% | EA | 1.00 |
| R189 | 136-05112-0062 |  |  | PF 51.1K EW 1\% | EA | 1.00 |
| R190 | 136-01433-0062 |  | RES | PF 143K EW 1\% | EA | 1.00 |
| R191 | 136-05112-0062 |  |  | PF 51.1K EW 1\% | EA | 1.00 |
| R192 | 131-00394-0013 |  | RES | CF 390K EW 5\% | EA | 1.00 |
| R193 | 136-06042-0062 |  | RES | PF 60.4K EW 1\% | EA | 1.00 |


| SYMBOL | PART NUMBER | FIND N0 | DESCRIPTION | UM | 0000 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| R194 | 133-00100-0076 |  | RES VA 500K QW 10\% | EA | 1.00 |
| R195 | 133-00100-0076 |  | RES VA 500K QW 10\% | EA | 1.00 |
| R196 | 133-00100-0076 |  | RES VA 500K QW 10\% | EA | 1.00 |
| R197 | 133-00100-0076 |  | RES VA 500K QW 10\% | EA | 1.00 |
| R198 | 131-00301-0023 |  | RES CF 300 QW 5\% | EA | 1.00 |
| R199 | 131-00301-0023 |  | RES CF 300 QW 5\% | EA | 1.00 |
| V101 | 134-05006-0002 |  | PHOTOCELL | EA | 1.00 |
| V102 | 134-05006-0002 |  | PHOTOCELL | EA | 1.00 |
|  | 009-05660-0060 |  | PC BOARD | EA | 1.00 |
|  | 016-01008-0004 |  | GLYPTAL 7526 BL | AR | 1.00 |
|  | 016-01040-0000 |  | COATING TYPE AR | AR | . 00 |
|  | 016-01122-0000 |  | EPOXY DEVCON 14250 | AR | . 00 |
|  | 047-02800-0002 |  | SHUTTER W/F | EA | 2.00 |
|  | 047-02844-0001 |  | SLIP RING BRSH W/F | EA | 4.00 |
|  | 088-00336-0008 |  | FLTR LAMP WHT/BLU | EA | 2.00 |
|  | 088-00337-0001 |  | HSG PICK OFF | EA | 2.00 |
|  | 089-02326-0000 |  | NUT TWIN 2-56 | EA | 2.00 |
|  | 089-05899-0004 |  | SCR PHP 2-56X1/4 | EA | 8.00 |
|  | 089-08012-0037 |  | WSHR INTL LK \#2 | EA | 8.00 |
|  | 091-00210-0000 |  | INSUL XSTR | EA | 1.00 |
|  | 092-05015-0006 |  | EYE FUNN .030X. 088 | EA | 4.00 |
|  | 150-00003-0010 |  | TUBING TFLN 24AWG | IN | 1.20 |
|  | 150-00005-0010 |  | tubing tFLN 20AWG | IN | 2.00 |
|  | 300-00826-0000 |  | PCB ASSY | RF | . 00 |

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DETAIL FOR NUG ( -0005 ) FLAUDR

(REF.)



sectron b-b

NOTES:


 SOLDER IN PLACE.
the longest lead of cri1 and cr15 is the anoom
4. TRIM FITLER (008--00336-0008) to LENGTH OF LamPS
5. THE Maximum hetaht of as is .300- aboue board
 MOUNT R71. 1255.025••OFF 日ORRo.
 Luse Miviral Topaue to Tighten screhs to auoto
. Install R77, r8z, and riz on solder stde of p.c. babro.

REWORK NOTES:
A. on back of p.c. bobro, connect j2 pin k to ez3.

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FIGURE 6-17 KI 525 P.C. BOARD ASSEMBLY


## FIGURE 6-17A KI 525 P.C. BOARD ASSEMBLY

Dwg. 300-00826-0000 R-4


FIGURE 6-18 KI 525 P.C. BOARD SCHEMATIC
(Dwg. 002-00306-0000 R-9)


FIGURE 6-18A KI 525 P.C. BOARD SCHEMATIC
(Dwg. 002-00306-0000 R-6)

### 6.18 KI 525 GLIDESLOPE PLATE ASSEMBLY

200-00643-0000 Rev. AA

| SYMBOL | PART NUMBER | FIND NO | DESCRIPTION | UM | 0000 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| CR117 | 007-07004-0000 |  | DIO L 5082-4480 | EA | 1.00 |
| REF100 | 300-00839-0000 |  | GLIDESLOPE PLATE | RF | . 00 |
|  | 013-00018-0000 |  | MAGNET | EA | 1.00 |
|  | 016-01013-0000 |  | VAC GREASE DC 976 | AR | . 00 |
|  | 016-01122-0000 |  | EPOXY DEVCON 14250 | AR | 1.00 |
|  | 019-02184-0000 |  | COIL 125T | EA | 1.00 |
|  | 047-04621-0003 |  | POLE MGNT | EA | 1.00 |
|  | 047-04621-0005 |  | POLE MGNT | EA | 1.00 |
|  | 073-00217-0002 |  | PLATE GS | EA | 1.00 |
|  | 073-00941-0001 |  | GS SUPPORT W/FIN | EA | 1.00 |
|  | 076-00694-0001 |  | SHAFT MAGNET W/F | EA | 1.00 |
|  | 089-05107-0004 |  | SCR, MACH, 2-56, F | EA | 4.00 |
|  | 089-08054-0030 |  | WSHR FLT STD . 128 | AR | . 00 |
|  | 089-08170-0030 |  | WSHR FLT STD . 128 | AR | . 00 |
|  | 090-00019-0000 |  | RING RTNR . 125 | EA | 1.00 |
|  | 147-05006-0008 |  | BEARING BALL | EA | 2.00 |
|  | 150-00018-0010 |  | TUBING SHRINK WHT | IN | 12.00 |

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FIGURE 6-19 KI 525 GLIDE SLOPE PLATE ASSEMBLY
(Dwg. 300-00839-0000 R-16)

(Dwg. 300-00839-0000 Old Revision)


[^0]:    7. APPLY RTV OVER END OF SHAFT AND ROUNDED END OF RETAINER RING. BE SURE RTV DOES NO
